

AHM36I-BDAK013x12

AHS/AHM36

ABSOLUTE ENCODERS

SICK
Sensor Intelligence.



Illustration may differ



Ordering information

Type	Part no.
AHM36I-BDAK013x12	1099377

Other models and accessories → www.sick.com/AHS_AHM36

Detailed technical data

Performance

Max. resolution (max. number of steps per revolution x max. number of revolutions)	13 bit x 12 bit (8,192 x 4,096)
Error limits G	0.35° (at 20 °C) ¹⁾
Repeatability standard deviation σ_r	0.2° (at 20 °C) ²⁾

¹⁾ In accordance with DIN ISO 1319-1, position of the upper and lower error limit depends on the installation situation, specified value refers to a symmetrical position, i.e. deviation in upper and lower direction is the same.

²⁾ In accordance with DIN ISO 55350-13; 68.3% of the measured values are inside the specified area.

Interfaces

Communication interface	SSI
Process data	Position
Initialization time	100 ms ¹⁾
Position forming time	125 μ s
SSI	
Code type	Gray
Code sequence parameter adjustable	CW/CCW configurable via cable
Clock frequency	2 MHz ²⁾
Set (electronic adjustment)	H-active (L = 0 - 3 V, H = 4,0 - Us V)
CW/CCW (counting sequence when turning)	L-active (L = 0 - 1 V, H = 2,0 - Us V)

¹⁾ Valid positional data can be read once this time has elapsed.

²⁾ Minimum, LOW level (Clock +): 500 ns.

Electrical data

Connection type	Cable, 8-wire, universal, 1.5 m
Supply voltage	4.5 ... 32 V DC
Power consumption	≤ 1.5 W (without load)

¹⁾ This product is a standard product and does not constitute a safety component as defined in the Machinery Directive. Calculation based on nominal load of components, average ambient temperature 40 °C, frequency of use 8760 h/a. All electronic failures are considered hazardous. For more information, see document no. 8015532.

Reverse polarity protection	✓
MTTFd: mean time to dangerous failure	230 years (EN ISO 13849-1) ¹⁾

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Mechanical data

Mechanical design	Blind hollow shaft
Shaft diameter	10 mm
Weight	0.2 kg ¹⁾
Shaft material	Stainless steel V2A
Flange material	Stainless steel V2A
Material, stator coupling	Stainless steel V2A
Housing material	Stainless steel V2A
Material, cable	PUR
Start up torque	1 Ncm
Operating torque	< 1 Ncm
Permissible movement static	± 0.3 mm (radial) ± 0.3 mm (axial)
Permissible movement dynamic	± 0.1 mm (radial) ± 0.1 mm (axial)
Moment of inertia of the rotor	23 gcm ²
Bearing lifetime	2.0 x 10 ⁹ revolutions
Angular acceleration	≤ 500,000 rad/s ²
Operating speed	≤ 6,000 min ⁻¹ ²⁾

¹⁾ Relates to devices with male connector connection.

²⁾ Self warming of 3.5 K per 1000 revolutions/min when applying note working temperature range.

Ambient data

EMC	According to EN 61000-6-2 and EN 61000-6-3
Enclosure rating	IP67 (according to IEC 60529) IP69K (according to IEC 60529)
Permissible relative humidity	90 % (Condensation not permitted)
Operating temperature range	-40 °C ... +100 °C
Storage temperature range	-40 °C ... +100 °C, without package
Resistance to shocks	100 g, 6 ms (according to EN 60068-2-27)
Resistance to vibration	20 g, 10 Hz ... 2,000 Hz (according to EN 60068-2-6)

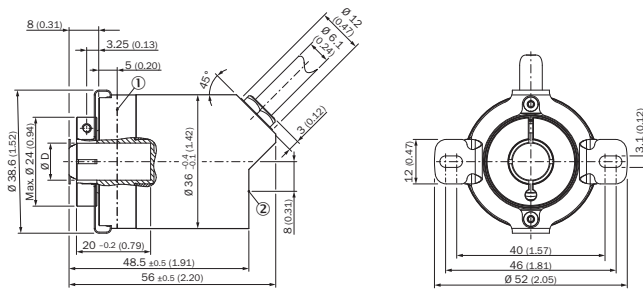
Classifications

ECl@ss 5.0	27270502
ECl@ss 5.1.4	27270502
ECl@ss 6.0	27270590
ECl@ss 6.2	27270590
ECl@ss 7.0	27270502
ECl@ss 8.0	27270502

ECI@ss 8.1	27270502
ECI@ss 9.0	27270502
ETIM 5.0	EC001486
ETIM 6.0	EC001486
UNSPSC 16.0901	41112113

Dimensional drawing (Dimensions in mm (inch))

Blind hollow shaft, cable outlet



Non-tolerated dimensions according to DIN-ISO 2768-mk

- ① Measuring point for operating temperature
- ② Measuring point for vibrations

PIN assignment




PIN, 8-pin, M12 male connector	Wire colors, cable outlet	Signal	Explanation
1	Brown	Data-	Interface signals
2	White	Data+	Interface signals
3	Black	V/R	Sequence for direction of rotation
4	Pink	SET	Electronic adjustment
5	Yellow	Clock+	Interface signals
6	Lilac	Clock-	Interface signals
7	Blue	GND	Ground connection
8	Red	+US	Operating voltage
Screen	Screen	Screen	Screen connected to housing on encoder side. Connected to ground on control side.

V/R Forwards / Reverse: This input programs the counting direction for the encoder. When it is not connected, this input is set to HIGH. If the encoder shaft is rotated clockwise (to the right) as viewed when facing the shaft, it counts in ascending order. If it should count in ascending order when the shaft is rotated counterclockwise (to the left), then this connection must be permanently set to LOW level (GND).

SET This input is for electronic zeroing. If the SET cable is set to US for more than 250 ms, the mechanical position corresponds to the 0 value, i. e., the predetermined SET value.

Recommended accessories

Other models and accessories → www.sick.com/AHS_AHM36

	Brief description	Type	Part no.
Flanges			
	Standard stator coupling, AHS/AHM36	BEF-DS16-AHX	2108615
Plug connectors and cables			
	Head A: female connector, M12, 8-pin, straight, A-coded Head B: - Cable: shielded	YF12ES8-0050S5586A	2097334
	Head A: male connector, M12, 8-pin, straight, A-coded Head B: - Cable: shielded	YM12ES8-0050S5586A	2097337

SICK AT A GLANCE

SICK is one of the leading manufacturers of intelligent sensors and sensor solutions for industrial applications. A unique range of products and services creates the perfect basis for controlling processes securely and efficiently, protecting individuals from accidents and preventing damage to the environment.

We have extensive experience in a wide range of industries and understand their processes and requirements. With intelligent sensors, we can deliver exactly what our customers need. In application centers in Europe, Asia and North America, system solutions are tested and optimized in accordance with customer specifications. All this makes us a reliable supplier and development partner.

Comprehensive services complete our offering: SICK LifeTime Services provide support throughout the machine life cycle and ensure safety and productivity.

For us, that is “Sensor Intelligence.”

WORLDWIDE PRESENCE:

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