## XTM-905 Extension Module, XPx-xxx Expansion Modules

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## Introduction

The XTM-905 Extension Module and XPx-xxx Expansion Modules provide additional physical inputs and outputs for DX-9100, DX-912x (LONWORKS® compatible), and DX-9200 (LONWORKS compatible) controllers. The XTM module provides the processing power and communications interface, and the XPx modules provide the analog and binary inputs and outputs. The XTM-905 replaces the XT-9100 extension module.

The DX controller communicates with the XTM- 905 via the XT Bus. By connecting XPx modules to each XTM-905, sets can be built with up to eight binary inputs/outputs and up to eight analog inputs/outputs, or up to sixteen binary inputs/outputs with eight counter functions. XPx modules provide triac outputs or relay outputs.
The status of all binary inputs and outputs and the value of analog outputs are indicated by Light-Emitting Diode (LED) displays built into the front panels of the modules. On XPx output modules with the manual override function, switches are provided to set outputs to manual mode for maintenance or emergency override purposes, if required.

The modules are designed for installation on standard DIN rails within a control cabinet. The outer dimensions of the modules also conform to a DIN standard for small, wall-mounting enclosures, which allow access to the indicator lamps and controls on the face of the module, yet protect the user from the internal wiring.


Figure 1: XTM-905 Extension Module and XPx-xxx Expansion Modules


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Figure 2: Extension Modules in Wall Mounting Enclosure


Figure 3: Extension Modules with Disconnect Terminals

## Features

Some of the features of these modules include:

- range of modules for flexible configuration of from 4 to 16 input/output points
- analog inputs 0-10V, 0/4-20 mA, Resistance Temperature Device (RTD) (Pt1000, Ni1000, A99, Pt100, and Ni100), or 5K ohm potentiometer
- analog outputs $0-10 \mathrm{~V}$ or $0 / 4-20 \mathrm{~mA}$, with LED indicators (and the option for manual override on the XPA-4x2 module)
- binary inputs with LED indicators
- binary triac outputs for switching 24 VAC with LED indicators and option for manual override
- binary relay outputs (for up to 250 VAC ) with LED indicators and option for manual override
- standard screw terminals or screw terminals with quick disconnect feature
- communications serial port (RS-485) for the XT Bus from the DX controller
- enclosure to DIN dimensions in self-extinguishing ABS (polycarbonite plastic material)
- DIN rail mounting
- parameter entry by personal computer and GX-9100 Graphic Configuration software (GX Tool)
- self-checking diagnostics for correct hardware configuration
- the ability to reside on XT Bus with XT-9100 extension models (eight extension models maximum on XT Bus)


## Application

The modularity of the design makes the extension modules ideal for distributed monitoring and control in conjunction with the DX-9100, DX-912x (LONWORKS compatible), or DX-9200 (LONWORKS compatible) controller, and reduces wiring costs to a minimum.
However, for large, centralized plant monitoring and control, the design enables high density installation in large control cabinets and requires no extra terminal blocks for field wiring. The modules are also available with disconnect terminals where required for conformance with local termination codes for supervisory systems.
The XTM-905 configuration and operating parameters are entered using a Personal Computer (PC), and configuration software is available from Johnson Controls. Configuration data is downloaded via the DX controller and is stored in EEPROM memory, which requires no battery support.

For details of the configuration requirements for the DX controller, refer to the DX-9100 Configuration Guide (LIT-6364030).

Note: XTM-905 modules are designed to connect to the XT Bus of a DX9100, DX-912x, or DX-9200 controller. For connection to the N2 Bus, use XTM-105 modules. Refer to the XTM-105 Extension Module, XPx-xxx Expansion Modules Technical Bulletin (LIT-6364200).


Figure 4: Metasys $\circledR^{\circledR}$ Network Control Module Application

The following chart lists and describes the different extension and expansion models that are detailed in this bulletin. Only those marked with an asterisk ( ${ }^{*}$ ) are available in North America.

Table 1: Model Codes

| Model/ <br> Ordering Code | Module Type | Description |
| :--- | :--- | :--- |
| XTM-905-5* | Extension Module | Communications interface and 24 VAC <br> supply |
| XPA-421-5 <br> XPA-431-5 | Expansion Module <br> Analog | 4 analog inputs (including PT100, Ni100 and <br> $0-5$ k ohm) |
| XPA-442-5 <br> XPA-452-5 | Expansion Module <br> Analog | 4 analog outputs with manual override |
| XPA-462-5 | Expansion Module <br> XPA-472-5 | Analog |

Note: The modules with disconnect terminals differ from the modules with standard screw terminals only in the extra height of the body needed to accommodate the larger disconnect terminal blocks. The characteristics and specifications of the two types of modules are otherwise identical. Where the technical descriptions or diagrams in this document name or show the standard screw terminal model codes, the discussion applies equally to the module with disconnect terminals.

## Design Considerations

Power is supplied to the XTM-905 by a standard 24 VAC power transformer (not supplied). Interconnecting ribbon cables supply 24 VAC power from the XTM to all the expansion modules connected to the XTM. Additional ribbon cables connect the XTM's communications bus from module to module. For environmental requirements, see Specifications and Technical Data in this document.

XTM-905
Hardware Configurations

An extension module assembled unit consists of one XTM-905 extension module and one or two expansion module positions known as XP1 and XP2.


Figure 5: Extension Module Configuration Positions
Each position may contain either one 8-point module or two 4-point modules. If 4-point modules are installed in either position, then the half positions will be referred to as XPxA and XPxB (for example, the two 4-point module positions in XP1 are called XP1A and XP1B).

Analog modules XPA-8x1-5 are 8-point modules and modules XPA-4xx-5 are 4 -point modules. All binary modules with inputs and outputs are considered to be 8 -point modules by the XTM- 905 . Only the binary modules XPE-444-5, XPE-454-5, XPE-464-5, and XPE-474-5, which have only four outputs, are considered 4-point binary modules by the XTM-905.

The following rules apply to the choice and placement of the various modules connected to one XTM:

- The position XP1 may contain analog type modules or binary type modules (but not both) and any binary inputs will have the counter function.
- The position XP2 is optional and may contain only binary type modules without the counter function.
- One 4-point binary module may be installed in the XP1 position (XP1A) if there is an 8-point binary module or no module in the XP2 position, and one 4-point binary module may be installed in the XP2 position (XP2A) when the XP1 position is filled. A 4-point binary module placed after XP1A will be configured as XP1B and not as XP2A, and three 4-point binary modules will be configured as XP1A, XP1B, and XP2A.
- An 8-point binary module placed after XP1A will be configured as XP2.
- The XP1 and XP2 positions each can be filled with two 4-point binary modules, or filled with an 8-point binary module.
Correct configurations can be built up from the currently available modules using Table 2 :

Table 2: Configuration Positions

| Position | Possible Modules |  | Notes |
| :---: | :---: | :---: | :---: |
| XTM | XTM-905 |  | An XTM-905 module is always required. |
|  | Analog | Binary |  |
| XP1 | XPA-8x1 | $\begin{aligned} & \hline \text { XPB-8x1 } \\ & \text { XPT- } 8 x 1 \\ & \text { XPM/L/E-4x1 } \\ & \text { XPT-4x1 } \\ & \text { XPE-4x4 }(x=0 . . .3) \end{aligned}$ | The B position cannot be used if an 8-point module already exists in XP1. <br> Binary inputs have the counter function. |
| XP1A | $\begin{aligned} & \text { XPA-4x1 } \\ & \text { XPA-4x2 } \end{aligned}$ | XPE-4x4 (x = 4...7) | If one XPA-4x1 and one XPA-402 are installed, the XPA-4×1 must be placed in XP1A. |
| XP1B | $\begin{aligned} & \text { XPA-4x1 } \\ & \text { XPA-4x2 } \end{aligned}$ | XPE-4x4 (x = 4...7) | The B position cannot be used if an 8-point module already exists in XP1. |
| XP2 <br> XP2A <br> XP2B | - | $\begin{aligned} & \text { XPB- } 8 \times 1 \\ & \text { XPT- } 8 \times 1 \\ & \text { XPM/L/E-4x1 } \\ & \text { XPT- } 4 \times 1 \\ & \text { XPE- } 4 \times 4(x=0 \ldots 3) \\ & \text { XPE- } 4 \times 4(x=4 \ldots 7) \\ & \text { XPE- } 4 \times 4(x=4 . . .7) \end{aligned}$ | The B position cannot be used if an 8-point module already exists in XP2. <br> The counter function is not available in this position. |

Front Panel Point Labels

Each point in an expansion module has a label for user identification of LED indicators and manual override switches, as shown in the table below. Note that the point labels are always the same on any one type of module and, therefore, the same point label may appear more than once in a given configuration. These labels are shown on the module diagrams in the Specifications and Technical Data section in this document.

Table 3: Front Panel Point Labels

| Module | Point Configuration | Front Panel Labels for: |  |
| :---: | :---: | :---: | :---: |
|  |  | LEDs <br> All Modules | Switches <br> Modules with Manual Override Feature Only |
| XPA-8x1 | 6 analog inputs <br> 2 analog outputs | $\stackrel{-}{\mathrm{AOT}-\mathrm{AOB}}$ | - |
| XPA-4x1 | 4 analog inputs | - | - |
| XPA-4x2 | 4 analog outputs | AO1-AO4 | $\Leftrightarrow, \mathrm{A} / \mathrm{M}, \stackrel{\text { u }}{ }$, ת |
| XPB-8x1 | 8 binary inputs | B11-BI8 | - |
| XPM-4x1 | 4 binary inputs <br> 2 binary outputs | $\begin{gathered} \mathrm{BI} 1-\mathrm{BI} 4 \\ \mathrm{BO} 1 \text { and } \mathrm{BO} 3 \end{gathered}$ | $2 \times(\mathrm{A} / \mathrm{M}, 0 / 1)$ |
| XPL/E-4x1 | 4 binary inputs 3 binary outputs | $\begin{gathered} \hline \mathrm{BI} 1-\mathrm{BI4} \\ \mathrm{BO} 1-\mathrm{BO} 3 \end{gathered}$ | $3 \times \mathrm{A} / 0 / 1$ |
| $\begin{array}{\|l\|} \hline \text { XPE- } 4 \times 4 \\ (x=0 \ldots 3) \\ \hline \end{array}$ | 4 binary inputs 4 binary outputs | $\begin{gathered} \mathrm{Bl1-BI4} \\ \mathrm{BO} 1-\mathrm{BO} 4 \end{gathered}$ | $4 \times \mathrm{A} / 0 / 1$ |
| $\begin{array}{\|l\|} \hline \text { XPE-4x4 } \\ (x=4 \ldots . .7) \\ \hline \end{array}$ | 4 binary outputs | BO1-BO4 | $4 \times \mathrm{A} / 0 / 1$ |
| XPT-4x1 | 4 binary inputs 4 binary outputs | $\begin{gathered} \mathrm{Bl1-BI4} \\ \mathrm{BO} 1-\mathrm{BO} 4 \end{gathered}$ | $4 \times \mathrm{A} / 0 / 1$ |
| XPT-8x1 | 8 binary outputs | B01-BO8 | - |

For configuration and monitoring purposes, each point in an expansion module is given a unique Item tag name based on the XP position, as shown in the table below:

Table 4: Point Tag Names

| Module | Point Configuration | Item Tag Names for Each Position |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 8-Point Analog Module in Position |  | XP1 (XTn...) |  | XP2 (XTn + 1...) |  |
| XPA-8x1 | 6 analog inputs 2 analog outputs |  |  |  |  |
| 4-Point Analog Modules in Position |  | XP1A | XP1B | XP2A | XP2B |
| XPA-4x1 <br> XPA-4x2 | 4 analog inputs <br> 4 analog outputs | $\begin{gathered} \mathrm{Al1-Al4} \\ \mathrm{AO} 1-\mathrm{AO} 4 \end{gathered}$ | $\begin{gathered} \mathrm{Al5-Al8} \\ \mathrm{AO} 5-\mathrm{AO} 8 \end{gathered}$ | - | - |
| 8-Point Binary Module in Position |  | XP1 (XTn...) |  | XP2 (XTn + 1...) |  |
| XPB-8x1 | 8 binary inputs | DI1-DI8 |  | DI1-DI8 |  |
| XPT-8x1 | 8 binary outputs | D01-DO8 |  | D01-DO8 |  |
| XPM-4x1 | 4 binary inputs 2 binary outputs | $\begin{gathered} \text { DI1-D14 } \\ \text { DO5, DO7 } \\ \hline \end{gathered}$ |  | $\begin{gathered} \text { DI1-DI4 } \\ \text { DO5, DO7 } \end{gathered}$ |  |
| XPL/E-4x1 | 4 binary inputs 3 binary outputs | $\begin{gathered} \text { DI1-DI4 } \\ \text { DO5-DO7 } \end{gathered}$ |  | $\begin{gathered} \text { DI1-DI4 } \\ \text { DO5-DO7 } \end{gathered}$ |  |
| XPE-4x4 (x = 0...3) | 4 binary inputs 4 binary outputs | $\begin{gathered} \text { DI1-DI4 } \\ \text { DO5-DO8 } \\ \hline \end{gathered}$ |  | $\begin{gathered} \text { DI1-D14 } \\ \text { DO5-DO8 } \end{gathered}$ |  |
| XPT-4x4 | 4 binary inputs <br> 4 binary outputs | $\begin{gathered} \hline \text { DI1-DI4 } \\ \text { DO5-DO8 } \end{gathered}$ |  | $\begin{gathered} \hline \text { DI1-DI4 } \\ \text { DO5-DO8 } \end{gathered}$ |  |
| 4-Point Binary Modules in Position |  | XP1A | XP1B | XP2A | XP2B |
| XPE-4x4 (x = 4...7) | 4 binary outputs | DO1-DO4 | D05-DO8 | DO1-DO4 | DO5-D08 |

Note: The full Item tag name in the DX controller is made up of the XT number and the point tag (XT1AI4, for example). The XT number for points in position XP2 is one greater than the XT number for points in XP1.

Analog Modules

The eight analog expansion modules currently available are listed in the table below. Of these eight modules, only the XPA-821-5 is available in North America.

Table 5: Analog Expansion Modules

| Model | Analog Inputs | Types | Analog Outputs | Types |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { XPA-821-5* } \\ & \text { XPA-831-5 } \end{aligned}$ | 6 analog inputs (Al1-Al6) | $\begin{aligned} & \text { 0-10 VDC } \\ & \text { 0/4-20 mA } \\ & \text { Ni1000 (Johnson Controls) } \\ & \text { Pt1000 (DIN) } \\ & \text { A99 } \end{aligned}$ | 2 analog outputs (without manual override) (AO7-AO8) | $\begin{aligned} & 1-10 \mathrm{VDC} \\ & 0 / 4-20 \mathrm{~mA} \end{aligned}$ |
| $\begin{aligned} & \text { XPA-421-5 } \\ & \text { XPA-431-5 } \end{aligned}$ | 4 analog inputs (Al1-Al4 or AI5-AI8) | ```0-10 VDC 0/4-20 mA Ni1000 (Johnson Controls, DIN, L\&G) Pt1000 (DIN) A99 Pt100 (DIN) Ni100 (DIN) 5K ohms potentiometer``` | - |  |
| $\begin{aligned} & \text { XPA-442-5 } \\ & \text { XPA-452-5 } \end{aligned}$ | - |  | 4 analog outputs (with manual override) (AO1-AO4 or AO5-AO8) | $\begin{aligned} & 0-10 \mathrm{VDC} \\ & 0 / 4-20 \mathrm{~mA} \end{aligned}$ |
| $\begin{aligned} & \text { XPA-462-5 } \\ & \text { XPA-472-5 } \end{aligned}$ | - |  | 4 analog outputs (without manual override) (AO1-AO4 or AO5-AO8) | $\begin{aligned} & 0-10 \mathrm{VDC} \\ & 0 / 4-20 \mathrm{~mA} \end{aligned}$ |

* Available in North America.

Input Expansion modules with analog inputs accept 0-10V, 0-20 mA, or passive
Characteristics RTD sensors by jumper configuration (XPA-8x1) or software configuration (XPA-4x1). For 0-20 mA DC inputs, a zero offset of 4 mA may be set by software configuration. The measurement unit of each RTD input can be configured for degrees Celsius or degrees Fahrenheit.
Voltage and current inputs, and 5 K ohm potentiometer inputs of the XPA-4x1 module can be ranged using the programmable range parameters as follows:

- lower end of range (LR) for $0 \mathrm{~V} / 0 \mathrm{~mA} / 4 \mathrm{~mA} / 0$ ohm
- higher end of range (HR) for $10 \mathrm{~V} / 20 \mathrm{~mA} / 5 \mathrm{~K}$ ohms

The analog input value is calculated as follows:

$$
A I=\frac{\% P R}{100} *(H R-L R)+L R
$$

where $\% P R=$ the analog value in percent of the physical range $(0-10 \mathrm{~V}$, $0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}, 0-5 \mathrm{~K}$ ohms).

Notes: For a potentiometer input, the value of $\% \mathrm{PR}$ is always related to a maximum resistance of 5 K ohms. For potentiometers with another resistance value, the maximum value of $\% \mathrm{PR}$ is as follows:

$$
\text { Maximum } \% P R=r * \frac{100}{5}
$$

where $r$ is the potentiometer resistance in K ohms.
The value of HR must correspond with a $\% \mathrm{PR}$ value of 100 or an equivalent input of 5 K ohms. For example, for a 2 K ohm potentiometer representing a physical quantity of 0-250 units, the value of HR must be set to:

$$
250 * \frac{5}{2}=625
$$

Voltage and current inputs from a differential pressure sensor, for example, can be linearized by a square root function which operates over the complete range of the input according to the following equation:

$$
A I=\sqrt{\frac{\% P R}{100}} *(H R-L R)+L R
$$

where $\% P R=$ the analog value in percent of the physical range (0-10V, 0-20 mA, 4-20 mA).
For all analog input types, a configurable filter is incorporated for the reduction of signal instability. The filter function is:

$$
F V_{t}=F V_{t-1}+\frac{1}{1+T_{s}}\left(A I_{t}-F V_{t-1}\right)
$$

where: $F V_{t}=$ Filtered Analog Value at current time
$F V_{t-1}=$ Filtered Analog Value at previous poll
$A I_{t} \quad=$ Actual Analog Value at current time
$T_{S} \quad=$ Filter Time Constant (seconds)
A $T_{S}$ value of 0 disables the filter.

Expansion modules with analog inputs will accept Ni1000, Pt1000, A99, and, on the XPA-4x1 only, Pt100 and Ni100 passive RTD sensors. The measurement ranges for these sensors are fixed, as shown in the table below:

Table 6: RTD Sensor Measurement Ranges

| RTD Sensor | Range |
| :--- | :--- |
| XPA-8x1 and XPA-4x1 | -45 to $+121^{\circ} \mathrm{C}\left(-50\right.$ to $\left.+250^{\circ} \mathrm{F}\right)$ |
| Ni 1000 Regular Sensor <br> (Johnson Controls) | +21 to $+288^{\circ} \mathrm{C}\left(+70\right.$ to $\left.+550^{\circ} \mathrm{F}\right)$ |
| Ni 1000 High Temperature Sensor <br> (Johnson Controls) | -50 to $+200^{\circ} \mathrm{C}\left(-58\right.$ to $\left.+392^{\circ} \mathrm{F}\right)$ |
| Platinum 1000 (DIN) Sensor | -50 to $+100^{\circ} \mathrm{C}\left(-58\right.$ to $\left.+212^{\circ} \mathrm{F}\right)$ |
| A99 Sensor (Johnson Controls) | -200 to $+850^{\circ} \mathrm{C}\left(-328\right.$ to $\left.+1562^{\circ} \mathrm{F}\right)$ |
| XPA-4x1 only | -60 to $+180^{\circ} \mathrm{C}\left(-76\right.$ to $\left.+356^{\circ} \mathrm{F}\right)$ |
| Platinum $\mathbf{1 0 0 0}$ and Pt $\mathbf{1 0 0}$ (DIN) Sensor | -50 to $+160^{\circ} \mathrm{C}\left(-58\right.$ to $\left.+320^{\circ} \mathrm{F}\right)$ |
| Ni $\mathbf{1 0 0 0}$ and Ni $\mathbf{1 0 0}$ (DIN) Sensor |  |
| Ni $\mathbf{1 0 0 0}$ (Landis \& Gyr) Sensor |  |

An offset parameter (OFS) is available, which is added to the analog input value to compensate for wiring resistance.

Expansion modules with analog inputs provide a 15 VDC supply for analog input sensors. The maximum current supplied from this power supply must not exceed 30 mA for the XPA-8x1 and 20 mA for the XPA-4x1.

A high and low alarm limit setting with alarm limit differential can be assigned to each analog input.


Figure 6: How Alarm Limits Function

## Output Characteristics

 Operation of the Analog Outputs (XPA-442 and XPA-452 Only)Expansion modules with analog outputs provide $0-10 \mathrm{VDC}, 0-20 \mathrm{~mA}$ or $4-20 \mathrm{~mA}$ outputs by software configuration. The type of output (voltage or current) is selected on the XPA- $8 \times 1$ by a jumper, and on the XPA- $4 \times 2$ by the output terminals used.

The output signal is proportional to the requested analog output value from 0 to $100 \%$.

The XPA-4x2 Analog Output module with manual override has four pushbutton switches on the right of its front panel and a vertical column of eleven LEDs on the left. The LEDs display either the current status of all four outputs or the current value of a selected output. The buttons are used to change the display mode and to manually override the output value of the currently selected output.


Figure 7: Front Panel of XPA-442
The functions of the four pushbutton switches are as follows:

- Use the top button labeled $\Leftrightarrow$ to toggle the display mode between status display for all four outputs and actual value display of the selected output.
- Use the button labeled $\mathrm{A} / \mathrm{M}$ to toggle the selected output between Automatic (DX-91x0) and Manual (local) operation. The button is active only in the status display mode and for the selected output.
- Use the two buttons labeled $\hat{\imath}$ and $\sqrt{ }$, depending on the display mode, either to select an output or to change the value of the currently selected output when it is in Manual mode. When selecting an output, either button, when repeatedly pressed or held down, cycles in the indicated direction through the four outputs ( AO 1 to AO 4 ).

In the status display mode, two LEDs for each output are used. The upper LED of the pair flashes when the output is selected. Otherwise, it is off. The lower LED of the pair is constantly lit when the output is in Manual mode, and is off when the output is in Automatic mode. Only one output may be selected at one time, but any number of outputs, or none, may be in Manual mode.


Figure 8: Output Status Display
By pressing the $\Leftrightarrow$ button, you can change the display mode to show the actual value of the selected output, which uses all 11 LEDs. The lowest LED represents an output of $0 \%$, and a full column of 11 lit LEDs represents $100 \%$. Each LED in the column represents a $10 \%$ step in the value of the output.

Note: When setting the value of an output in Manual mode, each press of the $\hat{\imath}$ or $\Omega$ button changes the value by $5 \%$. Therefore, you may have to press a button twice to see a change in the displayed value.

If no button is pressed within a period of one minute, the display automatically returns to a quiescent state where only the lowest LED is on. Pressing any button will restore the display to operational mode.

Binary Input Modules

The two 8-point binary input expansion modules currently available are listed in the table below:

Table 7: Eight-Point Binary Input Expansion Modules

| Model | Binary Inputs | Counters (XP1 only) |
| :--- | :--- | :--- |
| XPB-821 | eight binary inputs | eight counters |
| XPB-831 | (DI1-DI8) | (CNT1-CNT8) |

The 24 VAC supply from the XTM module powers the XPx binary inputs. Per the software configuration, the input is active when connected to the binary input common by the closing of an external potential-free contact (normally open), or when disconnected from the common by the opening of an external, normally-closed contact. The red LED is lit when the corresponding input is active. Eight LEDs indicate the status of each input on the binary expansion module.

A binary input may be defined as maintained or pulse type by software configuration. With maintained type contacts, the status reported by the XTM follows the status of the contact. With pulse type contacts, the XTM sets and resets the status at each pulse of the input contact. This type is recommended only for manual override functions, such as in lighting control, where the user gets confirmation of the override request by a verifiable response.

## Counter

 FunctionThe counter function is provided for the binary expansion module if installed in position XP1. The number of input contact transitions required to increment the counter can be set in the XTM module. The counter values are stored in 4-byte memory locations in Random Access Memory (RAM, Items CNT1-CNT8), and, on power failure, the values are automatically saved in EEPROM and then restored to RAM when power returns. The pulse frequency at the input should not exceed 25 Hz and the pulses must have a minimum On time of 20 ms , and a minimum Off time of 20 ms .

For consistency with the DX controller display, the counters will roll over at the decimal value of $9,999,999$.

## Binary Output Modules

The 26 currently available binary relay expansion modules are listed in the table below. Only those marked with an asterisk (*) are available in North

America.

Table 8: Binary Relay Expansion Modules

| Model with Manual Override | Model without Manual Override | Binary Inputs | Binary Outputs | Output Type |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { XPM-401-5 } \\ & \text { XPM-411-5 } \end{aligned}$ | $\begin{aligned} & \text { XPM-421-5 } \\ & \text { XPM-431-5 } \end{aligned}$ | 4 | 2 | Momentary Relay |
| $\begin{aligned} & \hline \text { XPL-401-5* } \\ & \text { XPL-411-5 } \end{aligned}$ | $\begin{aligned} & \text { XPL-421-5 } \\ & \text { XPL-431-5 } \end{aligned}$ | 4 | 3 | Magnetically Latching Relay |
| $\begin{aligned} & \hline \text { XPE-401-5* } \\ & \text { XPE-411-5 } \end{aligned}$ | $\begin{aligned} & \text { XPE-421-5 } \\ & \text { XPE-431-5 } \end{aligned}$ | 4 | 3 | Electrically Latching Relay |
| $\begin{aligned} & \hline \text { XPE-404-5* } \\ & \text { XPE-414-5 } \end{aligned}$ | $\begin{aligned} & \text { XPE-424-5 } \\ & \text { XPE-434-5 } \end{aligned}$ | 4 | 4 | Electrically Latching (On/Off) or Momentary (Pulse) Relays (Configurable) |
| $\begin{aligned} & \hline \text { XPE-444-5 } \\ & \text { XPE-454-5 } \end{aligned}$ | $\begin{aligned} & \text { XPE-464-5 } \\ & \text { XPE-474-5 } \end{aligned}$ | - | 4 |  |
| XPT-404-5 <br> XPT-411-5 | $\begin{aligned} & \text { XPT-421-5 } \\ & \text { XPT-431-5 } \end{aligned}$ | 4 | 4 | 24 VAC Triac |
| - | $\begin{aligned} & \hline \text { XPT-861-5* } \\ & \text { XPT-871-5 } \end{aligned}$ | - | 8 |  |

## Input Characteristics

## Counter Function

## Binary Output Characteristics (XPM/L/E-4x1)

## Momentary Relays (XPM)

## Magnetically Latched Relays (XPL)

Binary inputs are powered by the XTM module. By software configuration, the input is active (set) when connected to the binary input common via an external potential-free contact (normally open), or when disconnected from the common via an external potential-free contact (normally closed). The green LED is lit when the corresponding input is active (set). Normally open contacts are recommended for all status feedback indicators.

Binary inputs may be defined as maintained or pulse type by configuration. With maintained type contacts, the binary input status follows the status of the contact, and this type is recommended for all status feedback indicators and alarm signals.
With pulse type contacts, the binary input status is set and reset at each pulse of the input contact.

The counter function is available for the four inputs of a binary expansion module in position XP1. The number of input contact transitions required to increment the counter on each input can be set in the XTM module. The counter values are stored in 4-byte memory locations in RAM (Items CNT1-CNT4), and, on power failure, the values are automatically saved in EEPROM and then restored to RAM when power returns. The pulse frequency at the input should not exceed 25 Hz , and the pulses must have a minimum On time of 20 ms , and a minimum Off time of 20 ms . The counters will roll over at the decimal value of $9,999,999$.

The binary outputs associated with binary output modules XPM/L/E-4x1 do not have to be configured, as the module always drives the output relays as momentary (XPM), magnetically latched (XPL), or electrically latched (XPE), according to the type of module. The only exceptions are the XPE- 4 x 4 modules (see Relays [XPE-4x4 Modules] and Triac Outputs [XPT-4x1 and XPT-8x1] later in this chapter).

Two contacts are provided for each binary output, one for the On command (1) and one for the Off command (0), and will change over momentarily upon request. The contacts are interlocked such that only one output can be active at one time, and the length of the active pulse is determined by configuration (default is 20 ms ). Activating the off command removes power from the holding circuit output terminal.

The change-over contacts for the binary output change state on command and remain in the commanded state ( 0 or 1 ) by a magnetic latch on the relay. The magnetically latched contacts do not change state on 24 VAC power loss.

Electrically Latched Relays (XPE, Except XPE-4x4 Modules)

Relays (XPE-4x4 Modules) and Triac Outputs (XPT-4x1 and XPT-8x1)

Manual Override Operation of the Binary Output Modules

The change-over contacts for the binary output change state on command and remain in the commanded On state (1) by electrical holding of the contacts. An electrically held closed contact goes to the Off state if the module loses 24 VAC power.

The binary outputs of XPE-4x4, XPT-4x1, and XPT- $8 \times 1$ modules are configurable as on/off or pulse outputs. Relay outputs have change-over contacts with a single supply terminal for all four outputs. Triac outputs are electrically separated. The contacts or triac of an output configured as an on/off binary output will close or open on command and will remain in the commanded state. If the module loses 24 VAC power, the triac will open, and the relay will go to the Off state.
The contacts or triac of an output configured as a pulse binary output will change state momentarily on each command (on or off). The length of the pulse is determined by configuration (default is 20 ms ).

The binary output modules with manual override have three to four switches (depending on the number and type of outputs) on the right side of their front panels. The switches on the XPL/E modules have three positions and latch in each position (up, middle, down). The switches on the XPM modules have two or three positions (up, middle, down).
However, since the outputs are momentary, some of the switches do not latch but are instead spring loaded to return to the middle position after they have been pushed either up or down.

By software configuration, the manual override operation may be disabled when the module is connected to an active DX controller. In this case, the manual override operation is enabled only when XT Bus communication fails and the module is in a Standalone mode.

The LEDs on the left side of the front panel show the last commanded state from the DX controller.


Figure 9: Front Panel of XPL/E-401 (Three Binary Outputs)

Each binary output on an XPL/E/T module has one switch with positions labeled A, 0 , and 1. The A position sets the output to Automatic mode, which means the output is controlled by the DX controller. Setting the switch to either 0 or 1 sets the output both to Manual mode and to the selected output state.


Figure 10: Front Panel of XPM-401 (Two Binary Outputs)
Each binary output on an XPM module has two switches, where the first switch has positions labeled $\boldsymbol{A}$ and $\boldsymbol{M}$, and latches in each position. The second switch has Positions $\boldsymbol{0}$ and $\boldsymbol{1}$, and is spring loaded to return to the middle position after having been pushed either up or down. The $\boldsymbol{A}$ position on the first switch sets the output to Automatic mode for control by the DX controller. The $\boldsymbol{M}$ position sets the output to Manual mode. Once in Manual mode, the second switch can be used to pulse the output to either State 0 or 1 .

## Installation

The XTM-905 must be supplied with a 24 VAC power source. All models are suitable for 50 Hz or 60 Hz through software configuration. The extension modules are then supplied with 24 VAC power from the XTM via the expansion module supply bus, which is connected with the ribbon cables provided.

Two modules (XTM-905 and XPA-8x1) require that hardware settings (jumpers and DIP switches) be made before power is supplied to the modules. See Commissioning and Troubleshooting in this document for instructions.

CAUTION: Shock hazard. Connections to the terminals of XPM, XPL, and XPE expansion modules may carry up to 250 VAC. Isolate before servicing.

## General Guidelines

While every reasonable precaution has been taken to prevent electrical disturbances from adversely affecting the operation of the modules, lack of attention to generally accepted control wiring installation practices can lead to module problems in high electromagnetic field environments. In general, follow the guidelines below:

- Do not mount the modules in heavy-duty switch gear cabinets or in cabinets with frequency converting or phase-cutting equipment.
- Low voltage wiring in electrical cabinets must be physically separated from line voltage and power wiring, and a distinctive color (e.g., white or pink) for each type of wiring is recommended.
- To avoid electrical interference in field cables:
- Keep input and output point cable runs as short as possible ( $<50 \mathrm{~m}$ [165 feet]).
- Use twisted pair cables.
- Run low voltage cables separately from line voltage/power cables (minimum 30 cm [12 inch] separation from $230 \mathrm{~V}, 30 \mathrm{~A}$ circuits).
- Do not run low voltage cables parallel to power cables for long distances ( $>3 \mathrm{~m}$ [10 feet]).
- Do not run cables close to transformers or high frequency generating equipment.
- Use shielded cable in high electromagnetic field environments. Ground the shield at one end, preferably at the cabinet housing the modules.
- For the communications bus (XT Bus), use a cable recommended for RS-485 transmission. The cable must be shielded and the shield grounded at one end only.
- Do not connect switched inductive loads to the 24 VAC transformer which supplies the modules, and cable each connected load from the transformer separately, as shown in the figure below:


Figure 11: Wiring of Modules to a 24 VAC Transformer

## Mounting and Wiring Instructions

Figure 12 shows the dimensions of the XTM-905 module. All other modules have the same dimensions except for those with disconnect terminals, which have the height indicated by dotted lines in this figure. When mounted on a DIN rail, the modules of an XTM device set must be placed side by side so that the overall width of the unit is the sum of the widths of the individual modules.


Figure 12: Module Dimensions

## Mounting

Snap the module onto the 35 mm DIN rail. To release the module, insert a screwdriver at the base of the module (Point A), pull down to release the retaining clip, and tilt the bottom of the module forward and up. Since the retaining clip is spring loaded, you can also remove the module without a screwdriver by carefully pushing the module up against the clip and then tilting the top forward to release the top lug from the DIN rail.

## Labels for Module Front Panels

DIN A4 sheets of 12 blank stickers per sheet are available for creating module labels. The stickers fit in the white-framed area in the middle of the module front panel, and the lines of text can be printed such that they line up with the LED indicators to show the function of each input and output. The sheets can be printed with a laser printer.


Figure 13: Module Label Showing Functions of Inputs/Outputs

## Wiring

Terminations are made via the terminal blocks on the upper and lower parts of the modules which accept a maximum of $1.5 \mathrm{~mm}^{2}$ (16 American Wire Gauge [AWG]) cable. See the figures in the Wiring Diagrams section for field wiring examples.

Connect the XT Bus (serial link) cable to the terminals provided on the XTM-905 module. Ground the shield of the cable at one end only. The maximum bus length is 1200 meters ( 3900 feet), and a maximum of eight XTM-905 modules may be connected. When the bus length is greater than 100 meters ( 328 feet), both ends of the XT Bus must be terminated with end-of-line resistors. When the bus length is less than 100 meters ( 328 feet), only the DX controller end of the bus must be terminated.


Figure 14: Connection Details for the XT Bus

The end-of-line-resistor is provided in the Version 1 DX controller and is connected by Jumper JP7. For Version 2 and LonWorks-compatible DX controllers, the end-of-line resistor is provided in the mounting base or frame. Refer to the DX-9100 Configuration Guide (LIT-6364030) for details.

Expansion modules are connected to the XTM and to each other with two 5-pin ribbon cables, which are supplied with the expansion modules. One ribbon cable is plugged into the connector at the top of the neighboring module to provide the expansion module communications bus from the XTM to each module. The second ribbon cable is plugged into the connector at the bottom of the neighboring module to provide 24 VAC power from the XTM to the expansion modules.

Note: A power watchdog circuit checks that power is getting to all modules; the XTM will not respond if there is a problem. In order for the power watchdog circuit to operate properly, you must make sure that the last expansion module connected to the XTM has the loopback (end-of-bus) jumper installed in the correct position on its connector for the 24 VAC module supply bus, as shown in the figure below. One jumper is supplied with each module, although only the last module will use the jumper.


Figure 15: Connecting Expansion Modules to the XTM-905

Complete all field wiring and connections to the XTM and XPx modules before applying power. The XTM processor will then automatically configure itself for the connected XPx expansion modules.

CAUTION: Possible equipment damage. The CMOS integrated circuits used in the modules are sensitive to static electricity. Take suitable precautions.

## Wiring Diagrams

The following wiring diagrams illustrate typical field wiring to the inputs and outputs of the various expansion modules. Table 9, at the end of this section, describes the terminal labels.

Notes: Loads connected to binary outputs should be supplied from a separate, properly sized transformer.

The following commons are electrically independent:

- Analog Input Common
- Analog Output Common
- 24 V Common/Binary Input Common
- XT Bus (RS-485)


Figure 16: XTM-905


* Only one 4-20 mA active sensor may be powered by the module.

Figure 17: XPA-4x1


Figure 18: XPA-4x2


* Only one 4-20 mA active sensor may be powered by the module.

Figure 19: XPA-8x1


Figure 20: XPB-8x1


Figure 21: XPM-4x1


Figure 22: XPL/E-4x1


Figure 23: XPE-4x4 (x = 0...3)


Figure 24: $X P E-4 \times 4(x=4 . . .7)$


Figure 25: XPT-4x1


Figure 26: XPT-8x1

Table 9: Terminal Labels

| Expansion Module | Label | Definition |
| :---: | :---: | :---: |
| XPA-8x1 | 15 V | Analog input +15 V voltage supply |
|  | Aln | Analog input signal |
|  | $\perp$ or AIC | Analog input common |
|  | AOn | Analog output signal |
|  | 1 or AOC | Analog output common |
| XPA-4x1 | -In | Analog input signal negative |
|  | + In | Analog input signal positive |
|  | U | Software programmable analog input source, +15 V for active sensors or current source for RTD sensors |
|  | $\perp$ or AIC | Analog input common |
| XPA-4x2 | Un or Vn | Analog voltage output signal |
|  | In | Analog current output signal |
|  | $\underline{1}$ or AOC | Analog output common |
| XPB/E/L/M | Bln | Binary input |
|  | C | Binary input common |
|  | BOn | Binary/multistate output relay supply |
|  | 0, I | Relay output states |
|  | $\overline{0}$ | Momentary relay output not 0 (0 NC holding circuit supply) |
| XPE4x4 | Bln | Binary input |
|  | C | Binary input common |
|  | BO | Binary output relay supply |
|  | n/0 | Normally Closed (N.C.) contact, BOn |
|  | n/l | Normally Open (N.O.) contact, BOn |
| XPT | BIn | Binary input |
|  | C | Binary input common |
|  | BOn | Binary output (isolated triac) |

## Software Configuration

Software configuration of the XTM-905 Extension Module is done as part of the DX controller configuration process, using the GX-9100 Graphic Configuration software (GX Tool). Refer to the GX-9100 Software Configuration Tools User's Guide (LIT-6364060) for full technical and operating details. This section explains the configuration process for users who want to understand the XTM database structure in more detail, and also gives information on how to verify and change the configuration using the SX Tool.

Description of Items

Item Address

Item Type

A configuration consists of a set of parameters which are stored in specific memory locations in the XTM-905. These memory locations are addressed and referenced using mnemonic names called Items. Each Item represents a specific memory location (address) and is of a specific type corresponding to its usage and the number of bytes of memory it represents.

Dynamic (changing) data, such as analog values, are stored in Random Access Memory (RAM). Configuration parameters are stored in EEPROM. Data stored in EEPROM is retained when the power is switched off.

The Item Table section in Appendix A:Item Table of this document gives a brief description of all the Items available within the module.

The address of each Item is shown in the Address column of the Item Table in both decimal and hexadecimal representation in the Dec. and Hex. subcolumns, respectively. To make it easier to find the Items in the table, the decimal Item Address is shown in parentheses throughout the rest of the configuration section (for example, Item XTS [dec. 69]).

The information stored in the Items can have one of several formats:

- Floating Point Numerical Items are real numbers, with a $\pm$ sign and decimal point. They refer to input or output values, limit values, etc. They are displayed and entered as numbers. These Items are shown in the Item Table with Float in the Type column.
- Integer Items are positive whole numbers used as scale factors. These Items are shown in the Item Table with 1 Byte in the Type column. Some integer values may be 2 bytes long, which is indicated in the Item Table with 2 Bytes in the Type column.
- Totalized Numerical Items are positive whole numbers. They refer to totalized values of pulse counters. They are displayed and entered as whole numbers without a sign or decimal point. These Items are shown in the Item Table with 4 Bytes in the Type column.
- Status Items are either 8- or 16-bit (1- or 2-byte) Items giving information on the current status or configuration of the inputs, outputs, and modules. Each bit of the Item has a specific meaning as described in the Item Table. These Items are shown in the Item Table with 8-bits or 16-bits in the Type column. In the table, the bit positions will be referenced using X8-X1 or X16-X1, and a line depicting the bit positions will be shown, as follows:

```
1 Byte = X8 X7 X6 X5 X4 X3 X2 X1
2 Bytes = X16 X15 X14 X13 X12 X11 X10 X9 X8 X7 X6 X5 X4 X3 X2 X1
```

Item Tag
Each Item in the Item Table has a unique, 3- or 4-character name or Tag, which is a mnemonic for the type and usage of the data stored at that memory location in the XTM-905.

The Items are shown in the Item Table with their mnemonic names in the Tag column.

## Read/Write Data

The Items shown in the Item Table fall into three basic categories:

- Input values and status Items of the XTM-905 that can be read, but not changed, by a supervisory system. These Items are shown in the Item Table with an $R$ in the $\mathbf{R} / \mathbf{W}$ (Read/Write) column.
- Variables in the XTM-905 that can be read and modified by Configuration Software or supervisory systems. These Items are shown in the Item Table with an $R / W$ in the $\mathbf{R} / \mathbf{W}$ (Read/Write) column. The $R / W$ may be followed by $(E)$, which indicates that the Item is stored in EEPROM and can only be written approximately 10,000 times.
- All other Items in the XTM-905 refer to configuration parameters of the module and contain information such as analog ranges, output type, etc. These Items should be changed only with the GX-9100 Graphic Configuration software (GX Tool) or SX Tool, and are indicated in the Item Table with $C N F$ in the $\mathbf{R} / \mathbf{W}$ (Read/Write) column. All configuration parameters are stored in EEPROM, and the restriction of approximately 10,000 write operations applies here also.

XTM-905 Type
Settings

Via the GX Tool
Select Edit and then Global Data. Enter the frequency as 50 or 60 Hz . The XTM frequency and the DX frequency are both defined here.

## Via the SX Tool

Set Bit X1 of Item XTS (dec. 69).

- X1 $=050 \mathrm{~Hz}$ power line
- $\mathrm{X} 1=160 \mathrm{~Hz}$ power line

Configure an XTM module. Select PM, XTMn, and an analog or digital configuration.
Then select the just configured XTMn and Data. Enter as appropriate:

- User Name (maximum 8 characters)
- Description (maximum 24 characters)


## Via the GX Tool

To download the XTM-905 devices, it is necessary to enter the XTM addresses. When performing a download through a DX controller, these addresses also will be loaded into the DX, and the controller will retransmit XTM data to its own XTM set. The XTM address is not stored in the XTM-905, but must be set on the address switches on the module.

Configure an XTM Module. Select PM, XTMn, then an analog or digital configuration. Then select the just configured XTMn and Data. At the Hardware Address field, enter the address (1-255) of the XTM-905 module.

## Via SX Tool

Refer to Extension Module Configuration in the DX-9100 Configuration Guide (LIT-6364030).

Maximum Time
Between Communications

## Operational Mode (SX Only)

XTM-905
Configuration
Settings
I/O Type and Map

When communication fails for the period set in this Item, the XTM-905 goes into communication failure state, indicated by a blinking Power LED on the front of the module. The default value is 60 seconds.

## Via the GX Tool

Configure an XTM module. Select PM, XTMn, and an analog or digital configuration. Then select the just configured XTMn and Data. At the Comm. timeout (sec) field, enter the value in seconds.

## Via the SX Tool

The Maximum Time Between Communications (in seconds) is entered at Item MTBC (dec. 86).

The operational mode of the XTM-905 can be seen at Item OPMO (dec. 01) with following status bits:
$\mathrm{X} 8=1$ PWR Power Failure. This bit is set when an XTM is powered up or when there is a serial interface communication failure.
The setting in Item XTS (dec. 69) Bit X2 (Output Hold/Reset on Communication Failure flag) is repeated in Item OPMO (dec. 01) Bit X7 (FAIL) so that it can be read by the DX controller. Both of these operational mode status bits are available in the DX configuration database.

## Via the GX Tool

The Input/Output type and map details are generated automatically by the GX-9100 Graphic Configuration Software when you have entered all I/O data for extension modules. It is then downloaded into the XTM-905 via the DX controller and XT Bus. (Refer to the Download/Upload section in this document.)

When in the GX Tool, select PM, XTMn, and an analog or digital configuration. If digital, define the module as 4DI4DO, 8DI, 8DO, XPM, XPL, or XPE. If analog, define it as $4 \mathrm{AI}, 4 \mathrm{AO}, 4 \mathrm{AI} 4 \mathrm{AO}, 8 \mathrm{AI}, 8 \mathrm{AO}$, or 6AI2AO. This defines Module XP1. If an XTM has 16 points (XP2 is connected), select the XTM box with the next highest index number to the configured module, select EXP and define it as 4DI4DO, 8DI, 8DO, XPM, XPL, or XPE. EXPn appears in the XTM box on screen, and the configured points appear to the left and right of the screen. Refer to Table 10 for the appropriate selections for the available XPx modules. Then define each point in the selected configuration in the same way as when defining the points in the DX controller. The following pages describe how to define each of the points individually.

Table 10: GX Tool Selection for Module Configuration

| XTM Module Configuration | GX Tool Selection |
| :---: | :---: |
| XPA-4x1 | 4AI |
| XPA-4x2 | 4AO |
| XPA-4x1 + XPA-4x2 | 4AI4AO |
| XPA-4x1 + XPA-4x1 | 8AI |
| XPA-4x2 + XPA-4x2 | 8AO |
| XPA-8x1 | 6AI2AO |
| XTM/EXP Module Configuration | GX Tool Selection |
| XPM-4x1 | XPM |
| XPL-4x1 | XPL |
| XPE-4x1 | XPE |
| XPE-4x4 ( $\mathrm{x}=0 . . .3$ ) | 4DIDO |
| XPE-4x4 ( $\mathrm{x}=4 . . .7$ ) | 8DO (Configure DO1-DO4 only.) |
| XPE-4x4 + XPE-4x4 ( $\mathrm{x}=4 \ldots . .7$ ) | 8DO |
| XPT-4x1 | 4DIDO |
| XPT-8x1 | 8DO |
| XPB-8x1 | 8DI |

## Via the SX Tool

Each extension module configuration is defined by the I/O types and map, which are configured in extension module Items IOMAP (dec. 77).
IOTYP (dec. 78) and IOMOD (dec. 79).

- The I/O map (IOMAP) defines which inputs/outputs (in pairs) on the extension module are used. Each extension module can be defined with eight used points, which normally reside in the XP1 (first) expansion module (Points I/O1-I/O8), defined in bits X1-X4.
When an extension module has an XP2 (second) Expansion Module with a further eight points, these points must be defined in bits X5-X8.
- The I/O type (IOTYP) defines which inputs/outputs (in pairs) are analog and which are digital. As the points on XP2 (if used) must be digital, only bits X1-X4 can be configured.
- The I/O mode (IOMOD) defines points as input or output (in pairs). Only those points declared as used in Item IOMAP will be monitored or controlled.

The combination of data in the Items IOMAP, IOTYP, and IOMOD completely defines the configuration of an extension module. When connected to a DX controller, an identical set of data must be entered into the Item database in the DX controller so that, when the DX and XTM-905 are connected and started up, the DX will compare databases and only send commands to the extension module if the data is identical, thus avoiding incorrect control actions.
Note: The database in the XTM-905 is designed to accept most configuration of inputs and outputs. All inputs and outputs that are physically connected through expansion modules must be configured, and only those points. If there is a difference between the physical configuration and the software configuration, the XTM-905 signals an error condition to the DX controller:

XTnERR $=$ Wrong hardware configuration
XTnHARD $=$ Hardware not connected or not responding

## Analog Input

 ConfigurationEach analog input is defined and configured by the following parameters:

- User name and description (GX Tool only)
- Input signal and range
- Measurement units (for RTD inputs)
- Square root
- Alarm on unfiltered value
- Alarm limits
- Filter time constant

Before you can determine the input signal and range, you must first decide if the input is active or passive; the remaining options depend on this choice. With the SX Tool, this information is entered into a number of Items.

## Setting the Input <br> as <br> Active/Passive

## AI User Name and Description (GX Tool Only)

## Via the GX Tool

Select XTnAIn, then Active or Passive.
Note: All AI points must be configured, even if not connected to a sensor, to enable the generation of a complete IO Map and to ensure correct operation with the DX controller.

## Via the GX Tool

Select XTnAIn and then Data. Enter as appropriate:

- User Name (maximum 8 characters)
- Description (maximum 24 characters)


## AI: Input Signal and Range

## Via the GX Tool

(You must first have selected whether the input is active or passive. See
the beginning of Analog Input Configuration.)
For active inputs, select XTnAIn and Data. At the Type of Active Input field, enter:
$0=0-10 \mathrm{VDC}$
$1=4-20 \mathrm{~mA}$
$2=0-20 \mathrm{~mA}$
Each analog input module channel performs the conversion of the input signal to a numeric value using the high range and low range.
Select XTnAIn and Data.
High Range $=$ Enter the equivalent number for reading at high input ( $10 \mathrm{~V}, 20 \mathrm{~mA}$ ).

Low Range $=$ Enter the reading at low input ( $0 \mathrm{~V}, 0 \mathrm{~mA}, 4 \mathrm{~mA}$ ).
For passive inputs, select XTnAIn, then Data. At the Type of Passive Input field, enter:

| $1=$ Ni1000 (Johnson Controls Type) | $6=$ Ni1000 (DIN) |
| :--- | :--- |
| $2=$ Ni1000 Extended Range | $7=$ Unused |
| $3=$ A99 (Johnson Controls Type) | $8=5 \mathrm{~K}$ Potentiometer |
| $4=\operatorname{Pt} 1000($ DIN $)$ | $9=\operatorname{Pt100}(\mathrm{DIN})$ |
| $5=\operatorname{Ni} 1000($ L\&G $)$ | $10=\mathrm{Ni} 100(\mathrm{DIN})$ |

(L\&G)
$10=\mathrm{Ni} 100(\mathrm{DIN})$

Note: Selections 5 to 10 on the screen are not available in an XTM-905 with an XPA-8x1 connected.

For Pt100 RTD inputs at the 3-Wire Pt100 field, enter:
$0=4$-wire or 2 -wire connection
$1=3$-wire connection
See Installation, Wiring Diagrams for details.
For all RTD inputs, the range of the displayed value is fixed according to the type of sensor.

For Potentiometer inputs, the range is determined as follows:
High Range (Potentiometer) = Enter the equivalent number for reading at 5 K ohms input.
Low Range $($ Potentiometer $)=$ Enter the reading at 0 K ohms input.

## Via the SX Tool

## Input type:

| $\mathrm{X} 7=0$ | $0-10$ volts or potentiometer |
| :--- | :--- |
| $\mathrm{X} 7=1$ | $0-20 \mathrm{~mA}$ or RTD |
| $\mathrm{X} 8=1$ | $\mathbf{2 0 \%}$ Suppression $(2-10 \mathrm{~V}$ or $4-20 \mathrm{~mA})$ |

## Linearization and Sensor Type:

| X12 X11 X10 X9 = 0000 | Linear (Active Sensor) |
| :---: | :---: |
| $\mathrm{X} 12 \mathrm{X} 11 \mathrm{X} 10 \mathrm{X} 9=0001$ | Ni 1000 RTD Regular Sensor (Johnson Controls) |
| $\mathrm{X} 12 \mathrm{X} 11 \mathrm{X} 10 \mathrm{X} 9=0010$ | Ni 1000 RTD High Temperature Sensor |
| $\mathrm{X} 12 \mathrm{X} 11 \mathrm{X} 10 \mathrm{X} 9=0011$ | RTD Sensor A99 (Johnson Controls) |
| $\mathrm{X} 12 \mathrm{X} 11 \mathrm{X} 10 \mathrm{X} 9=0100$ | RTD Sensor Platinum 1000 (DIN) |
| $\mathrm{X} 12 \mathrm{X} 11 \mathrm{X} 10 \mathrm{X} 9=0101$ | Ni 1000 RTD Sensor (L\&G)* |
| $\mathrm{X} 12 \mathrm{X} 11 \mathrm{X} 10 \mathrm{X} 9=0110$ | Ni 1000 RTD Sensor (DIN)* |
| $\mathrm{X} 12 \mathrm{X} 11 \mathrm{X} 10 \mathrm{X} 9=1000$ | Linear - Potentiometer 5K ohms* |
| $\mathrm{X} 12 \mathrm{X} 11 \mathrm{X} 10 \mathrm{X} 9=1001$ | RTD Sensor Platinum 100 (DIN)* |
| X12 X11 X10 X9 = 1010 | Ni 100 RTD Sensor (DIN)* |
| $\mathrm{X} 15=0$ | RTD 2- or 4-wire connection* <br> (Default for linear sensors) |
| $\mathrm{X} 15=1$ | RTD 3-wire connection* |
|  | * For XPA-4x1 only |

Note: For RTD Sensor Measurement Ranges, refer to Table 6.

Each analog input channel performs conversion of the input signal to a raw value as a function of factory set calibration constants.

For active inputs and potentiometer inputs, a numeric value expressed in engineering units is then obtained using the input's high range at Items $\operatorname{HRn}(\mathrm{n}=1-8$ at dec. Addresses 89, 97, 105, 113, 121, 129, 137, and 145) and the input's low range at Items LRn ( $\mathrm{n}=1-8$ at dec. Addresses 90, 98, $106,114,122,130,138$, and 146).
For RTD inputs, the range of the temperature value is fixed according to the type of sensor and the units of measurement.

## Al: Measurement Units

## Via the GX Tool

The selection of Celsius or Fahrenheit is set in the Global Data of the DX controller (select Edit, then Global Data. At the Temperature Units field, select Celsius or Fahrenheit).

To set the measurement units of active inputs, select XTnAIn, Data, and then enter in the Measurement Units field:
$0=$ None
$1=$ Temperature ( C or F as entered in Global Data)
$2=$ Percent (\%)
Note: The units of an active input are not only used by the Version 1 DX-9100 Controller for the front panel display, but also may be entered for informational purposes.

## Via the SX Tool

The measurement units for the eight possible inputs ( $\mathrm{n}=1$ to 8 ) can be configured in Item AITn (dec. Addresses 88, 96, 104, 112, 120, 128, 136, and 144).

The unit of each analog input can be selected with the following bits (for RTD inputs, Celsius or Fahrenheit must be selected):

| X4 X3 X2 X1 $=0000$ | No Units |
| :--- | :--- |
| X4 X3 X2 X1 $=0001$ | Celsius |
| X4 X3 X2 X1 $=0010$ | Fahrenheit |
| X4 X3 X2 X1 $=0011$ | Percent or potentiometer |

Changing individual temperature units for each AI only can be done using the SX Tool.

AI: Enable Square Root

## Unfiltered Value

Al: Alarm on

AI: Alarm Limits

This function allows the linearization of a differential pressure signal from a $0-10 \mathrm{VDC}$ or $0 / 4-20 \mathrm{~mA}$ active sensor.

## Via the GX Tool (Option Only Available with Active Sensor)

Select XTnAIn and Data. At the Square Root field, enter 0 for No or 1 for Yes (to enable the square root calculation).

## Via the SX Tool (Operative Only with Active Sensor)

Select Item AITn.
X5 = $1 \quad$ Enable Square Root of Input.
X5 $=0 \quad$ Disable Square Root of Input.

An alarm from the High Limit (HIAn) and Low Limit Alarm (LOAn) values may be generated from the unfiltered or filtered input. (See AI: Filter Time Constant in this document.)

## Via the GX Tool

Select XTnAIn and Data. At the Alarm Unfiltered field, enter 0 for No (Alarm on Filtered Value) or 1 for Yes (Alarm on Unfiltered Value).

## Via the SX Tool

Select Item AITn.
X6 $=0 \quad$ Alarm on Filtered Value
X6 $6=1 \quad$ Alarm on Unfiltered Value

The high limit and the low limit define at which levels the analog input reading generates an alarm, either for remote monitoring or for internal use within the control sequences in the DX controller.
Note: The limits cannot be deleted. If you do not want alarms, enter limits beyond the range.

## Via the GX Tool

Select XTnAIn, then Data. At the respective field, enter the limit:
High Limit $\quad=$ Enter value at which input should go to high alarm.
Low Limit $\quad=$ Enter value at which input should go to low alarm.
Limit Differential $=$ Enter value by which the input must change below the high limit or above the low limit to reach the normal state.

## Via the SX Tool

The high limits at Items HIAn ( $\mathrm{n}=1-8$ at dec. Addresses 91, 99, 107, 115, 123, 131, 139, and 147) and the low limits at Items LOAn ( $\mathrm{n}=1-8$ at dec. Addresses $92,100,108,116,124,132,140$, and 148) define at which levels the analog input reading will generate an alarm for remote monitoring purposes. These Items also may be set via the DX controller by a supervisory system, with the restriction that they are stored in EEPROM and only can be written approximately 10,000 times.

By setting bit X6 of Items AITn (dec. Addresses 88, 96, 104, 112, 120, 128,136 , and 144) to 1 , the alarm will be generated from the unfiltered input.
The differentials on alarm limits are adjustable with Items ADFn ( $\mathrm{n}=1-8$ at dec. Addresses $93,101,109,117,125,133,141$, and 149).

## Al: Filter Time Constant

Use the Filter Time Constant Ts (seconds) to filter out any cyclic instability in the analog input signals.

## Via the GX Tool

Select XTnAIn, then Data. At the Filter Constant (sec) field, enter a number within the recommended range of 0 to 10 .

## Via the SX Tool

Enter the Filter Time Constant at Item FTCn (dec. Addresses 94, 102, $110,118,126,134,142$, and 150).

Al: Offset Value
Use an offset value, in the units of the analog input, to compensate for analog transmitters that do not have a true zero output, or for wiring resistance to RTD sensors. The offset value is added to the analog value calculated from the range parameters.

## Via the GX Tool

Select XTnAIn and Data. At the Offset Value field, enter a number in the units of the analog input.

## Via the SX Tool

The offset value is defined in Items OFSn ( $\mathrm{n}=1-8$ at dec. Addresses 95, $103,111,119,127,135,143,151)$. Enter a value in the units of the analog input.

AI Notes

## Binary (Digital) Input Configuration

## DI User Name and Description (GX Tool Only)

1. When the XTM-905 is connected to the DX controller, you can view the AI value and alarm limits from the DX front panel. See Display Panel and Keypads in the DX-9100 Extended Digital Controller Technical Bulletin (LIT-6364020).
2. Analog input values can be read via the SX Tool at Item AIn (dec. 12 to dec. 19).
3. Analog input alarm status can be seen via the SX Tool at Item AIS (dec. 11), Bit X1, X3...X15 for high alarm condition and X2, X4 $\ldots \mathrm{X} 16$ for low alarm condition.
4. Configure all AIs as active or passive, whether they are used or not. A configured AI is shown by an inner border around its function box on the screen of the GX Tool.

An XTM-905 can accept up to 16 digital inputs, depending on the hardware configuration. The first eight digital inputs are connected to XP1, and the next eight digital inputs to XP2.
Define and configure each digital input by the following parameters:

- User name and description (GX Tool only)
- Input type
- Counter prescaler

Inputs may be defined as maintained or pulse type. With maintained type contacts the extension module status follows the status of the contact. With pulse type contacts, the extension module sets and resets the status at each pulse of the input contact. The inputs also may be configured for normally open or normally closed contacts, normal being defined as the inactive or 0 state.

## Via the GX Tool

Select XTnDIn, then Data. Enter as appropriate:
User Name (maximum 8 characters)
Description (maximum 24 characters)

## DI: Input Type

## Via the GX Tool

Select XTnDIn, then Data. At the Digital Input Type field, enter 0 for maintained contact or 1 for pulse contact. At the Normally Closed Contact field, enter 0 for normally open and 1 for normally closed.

## Via the SX Tool

The input type for the $2 \times 8$ possible inputs can be configured in Item DIT1 for XP1 (dec. 64) and in Item DIT2 (dec. 65) for XP2, bits X1-X8 for D11-DI8, as follows:
$0=$ Maintained Contact
$1=$ Pulse Contact
The normally open/normally closed contact type for each binary input can be configured in Item NOC1 (dec. Address 46) for XP1 and in Item NOC2 (dec. Address 47) for XP2, bits X1-X8 for xDI1-xDI8, as follows:
$0=$ Normally Open Contact
1 = Normally Closed Contact

## DI: Counter Prescaler

The digital input transitions of XP1 are counted as follows:


Figure 27: Counting Order of Digital Input Transitions
A count transition occurs when the number of positive transitions of the digital input (DIn) equals the value of the prescaler ( PCn ). The pulse counter (CNTn, $\mathrm{n}=1-8$ ) counts the count transitions up to a maximum of $9,999,999$, after which the count automatically resets to 0 .
Note: Counters are available only in the XP1 location.

## Via the GX Tool

Select XTnDIn, then Data. At the Prescaler (counts) field, enter a number from 1 to 255 .

## Via the SX Tool

Enter the prescaler at Item PCn (dec. 48-55), within the range 1-255.

DI Notes

1. When the XTM-905 is connected to the DX controller, you can view the DI status and counter values from the DX front panel. See Display Panel and Keypads in the DX-9100 Extended Digital Controller Technical Bulletin (LIT-6364020).
2. View the status of the digital inputs at Item DIS1 (dec. 09), bits X1-X8, and Item DIS2 (dec. 10), bits X1-X8.

## Analog Output Configuration

AO User Name and Description (GX Tool Only)

Define and configure each analog output by the following parameters:

- User name and description (GX Tool only)
- Output type
- Output ramp time (XPA-4x2 only)

The following parameters are defined in the DX controller for the analog output:

- Source
- Range


## Via the GX Tool

Select XTnAOn and then Data. Enter as appropriate:

User Name (maximum 8 characters)
Description (maximum 24 characters)

## AO: Output Type Via the GX Tool

Select XTnAOn and Data, then enter at the Type of Output field:
$0=$ disabled
$1=0-10 \mathrm{VDC}$
$2=0-20 \mathrm{~mA}$
$3=4-20 \mathrm{~mA}$

## Via the SX Tool

The output type is configured in Item AOT (dec. 87) in bit pairs X2-X1, X4-X3, up to X16-X15 for Outputs 1-8, respectively. To define the output signal type, set the bits as follows (for Output 1):
X2 X1 $=00 \quad$ Output Disabled
$\mathrm{X} 2 \mathrm{X} 1=01 \quad$ Output $0-10 \mathrm{~V}$
$\mathrm{X} 2 \mathrm{X} 1=10 \quad$ Output $0-20 \mathrm{~mA}$
$\mathrm{X} 2 \mathrm{X} 1=11 \quad$ Output $4-20 \mathrm{~mA}$
Set the other outputs in a similar way.

AO: Source

## AO: Range

AO: Output
Ramp Time
(XPA-4x2 Only)

The source of the analog output signal is defined in the DX controller.

## Via the GX Tool

Select XTnAOn, then Data, then the Source Point field. Enter * and select the required source variable.

## Via the SX Tool

Refer to Extension Module Configuration in the DX-9100 Configuration Guide (LIT-6364030).

The AO range of the analog output is defined in the DX controller. The high range defines the level of control source signal that corresponds to an output of $100 \%$.
The low range defines the level of control source signal that corresponds to an output of $0 \%$.

When the source point is equal to the high range, the output is at the maximum signal $(10 \mathrm{~V} / 20 \mathrm{~mA})$. When the source point is equal to low range, the output is at the minimum signal $(0 \mathrm{~V}, 0 / 4 \mathrm{~mA})$.

## Via the GX Tool

Select XTnAOn and Data, then enter the desired values in the High Range and Low Range fields.

## Via the SX Tool

Refer to Extension Module Configuration in the DX-9100 Configuration Guide (LIT-6364030).

The analog output ramp time defines the maximum rate of change of the output in units of 5 milliseconds for a $1 \%$ change. A value of 10 defines a rate of 50 milliseconds for a $1 \%$ change or 5 seconds for a $100 \%$ (full scale) change.

## Via the GX Tool

Select XTnAOn and Data, then enter the desired rate at the Output Ramp Time field.

## Via the SX Tool

The Analog Output Ramp Time is entered in Item AORn ( $\mathrm{n}=1-8$ at dec. Addresses 152-159). The value entered determines the time required, in increments of 5 milliseconds, for a $1 \%$ change in the analog output value in both manual and automatic modes. For example, when a value of 20 is entered, each $1 \%$ change in analog output value will require 100 milliseconds, and a change from 0 to 100 will take 10 seconds.

AO Notes

## Binary (Digital) Output Configuration

DO User Name and Description (GX Tool Only)

1. When the XTM-905 is connected to the DX controller you can view and override the AO value from the DX front panel. See Display Panel and Keypads in the DX-9100 Extended Digital Controller Technical Bulletin (LIT-6364020).
2. The analog output values can be read in percent at Item AO1-8 (dec. 20-27) with the SX Tool.
3. The manual override status of analog outputs is not available in the DX controller.

The following parameters define and configure each digital output:

- User name and description (GX Tool only)
- Output type
- Pulse time
- Status on communication failure
- Status after power failure
- Disable manual override in Supervisory mode
- Manual Override status

The Source parameter is defined in the DX controller for the digital output.

## Via the GX Tool

Select XTnDOn and then Data. Enter as appropriate:
User Name (maximum 8 characters)
Description (maximum 24 characters)

## DO: Output Type

Via the GX Tool
Select XTnDOn, then select On/Off or Pulse. For the Pulse type, the output switches for a configurable pulse time for each state transition of the command output. For XPM-4x1, XPL-4x1, and XPE-4x1 modules, the hardware determines the type of output, and you should select Pulse as a default.

## Via the SX Tool

The output type can be set in Item DOT1 (dec. 66) for XP1 and Item DOT2 (dec. 67) for XP2 as follows ( $\mathrm{n}=1-8$ ):
$\mathrm{Xn}=0 \quad$ On/Off Type
Xn=1 Pulse Type
Note: This setting is required only for binary outputs on XPE-4x4, XPT-4x 1, and XPT-8x1 modules. For XPM, XPL, and other XPE modules, the type of output is determined by the module.

DO: Pulse Time This parameter is set once for all pulse type outputs in the XTM-905.

## Via the GX Tool

Select XTn and Data, then enter a value in the Digital Output Pulse Time field. The valid range is 1 to 250 ( 5 milliseconds to 1.25 seconds pulse time).

## Via the SX Tool

The digital output pulse time is used by XPM-4xx modules, and by XPE4 x 4, XPT- 4 x 1 , and XPT- 8 x 1 modules configured with pulse type outputs, to determine the output pulse width. It is defined in Item DOPT (dec. 68) in units of 5 milliseconds. The default value is 4 , which represents a pulse time of 20 milliseconds.

Note: All connected DO points must be configured to ensure correct operation with the DX controller. When a single XPE-4x4 $(x=4 \ldots 7)(4 D O)$ relay module is connected, select 8 DO on the GX Tool and define outputs DO1-DO4 only.

## DO: Status on

 Comm. FailureDO: Status After
Power Failure

## Via the GX Tool

First configure an XTM module. Select PM, XTMn, and an analog or digital configuration. Then select the just configured XTMn and Data.
To set this flag, at the DO Status on Comm. Fail (communication failure) field, enter 0 or 1 .

When this field is set to 0 , the digital outputs are switched off upon an XT Bus failure, and the corresponding Item values are reset to zero.

When set to 1 , the digital outputs hold their current state upon an XT Bus failure.

## Via the SX Tool

The Output Hold/Reset on Communication Failure flag is set at Bit X2 of Item XTS (dec.69).
$\mathrm{X} 2=0 \quad$ Output reset upon communication failure.
$\mathrm{X} 2=1 \quad$ Output hold upon communication failure.

## Via the GX Tool

Select XTMn and Data. At the DO status after power fail field, enter 0 or 1 .

When this field is set to 0 , all digital outputs on the XTM are switched off on a power failure, and remain off when power is restored.
When set to 1 , all digital outputs on this XTM are restored to their previous state when power returns.

## Via the SX Tool

The power fail/restore mode for each output is defined in Item DOR1 (dec. 70) for XP1 and Item DOR2 (dec. 71) for XP2, as follows ( $\mathrm{n}=1-8$ ):
$\mathrm{Xn}=0 \quad$ Reset output n to 0 at power up.
$\mathrm{Xn}=1 \quad$ Restore previous condition (at power-down) to output $n$ when power is restored.

The restore mode does not apply to pulse outputs on XPE-4x4, XPT-4x1, and XPT-8x1 modules, nor to XPL-xxx modules that remain latched through power failure and restoration.

DO: Disable Manual Override in Supervisory Mode

## Via the GX Tool

Select XTMn and Data. At the Disable Man. Ovr. in Sup. field, enter 0 or 1 . When the field is set to 0 , Manual Override is enabled in all connected modules at all times.
When set to 1 (disable), Manual Override is disabled in all connected modules when the XTM is communicating with the DX controller. Manual Override is still active when the XTM module is not communicating with the DX controller.

## Via the SX Tool

The Manual Override Enable mode for each output on a module with the manual override feature is defined in Item MOE1 (dec. 40) for XP1 and Item MOE2 (dec. 41) for XP2, as follows ( $\mathrm{n}=1-8$ ):
$\mathrm{Xn}=0 \quad$ Manual Override Enable in Supervisory and Standalone mode
$\mathrm{Xn}=1 \quad$ Manual Override Enable in Standalone mode only

There are two options for reading and displaying the manual override status of the connected XPx modules at the DX controller. The XPx modules must have binary inputs DI1-DI4 for this feature. Options 1 and 2 may be selected for XP1 and XP2 independently.
Option 1: The manual override status of outputs DO5-DO8 can be read as binary inputs, DI1-DI4. In this case, the physical binary inputs cannot be used.
Option 2: The manual override of one or more outputs DO5-DO8 can be read in binary input DI4. In this case, the individual manual override status is not indicated, but only one physical binary input (DI4) cannot be used.

## Via GX Tool

Select XTMn and Data for XP1, and EXPn and Data for XP2. Enter a 1 in the field Man. Ovr. status in DI1-4 or Any Ovr. status in DI4, as required.

## Via SX Tool

The following items must be set for the two options:

- Manual Override Status of DO5-DO8 in DI1-DI4: Items DMI1 (dec. 42), DMI2 (dec. 43), DML1 (dec. 83), and DML2 (dec. 84) - set all bits.
- Any Manual Override Status of DO5-DO8 in DI4: Items DCM1 (dec.81), DCM2 (dec. 82), DML1 (dec. 83), and DML2 (dec. 84) - set each item to 00001000 (Bit 4 set, all other bits at 0 ).

The source of the digital output signal is defined in the DX controller.

## Via the GX Tool

Select XTnDOn, Data, and then the Source Point field. Enter * and select the required source variable.

## Via the SX Tool

Refer to Extension Module Configuration in the DX-9100 Configuration Guide (LIT-6364030).

1. When the XTM-905 is connected to the DX controller, you can view and override the DO value from the DX front panel. See Display Panel and Keypads in the DX-9100 Extended Digital Controller Technical Bulletin (LIT-6364020).
2. If so configured, the manual override status of digital outputs can be viewed as digital inputs from the DX front panel. See DO: Manual Override Status above.
3. The digital output status can be seen at Item DOS1 (dec. 07) for XP1 and Item DOS2 (dec. 08) for XP2, bits X1-X8 for outputs DO1-8 with the SX Tool.
4. A configured DO is shown by an inner border around its function box.

Configure all DOs as On/Off or Pulse, whether they are used or not. The only exception is for the 4-output relay module (XPE-4x4) ( $x=4 \ldots 7$ ). When only one module is installed, select 8DO, but only configure DO1-DO4. When two modules are installed, configure both as one 8DO module, and configure DO1-DO8.

Configure the XPM-4x1, XPL-4x1, and XPE-4x 1 modules as On/Off. The hardware determines the type of output on these modules.

## Specifications and Technical Data

This section lists the specifications and technical data for all available modules. All of the modules are available in Europe. Eight of the modules are available in North America. The Europe-only modules are labeled in the heading at the top, left corner of their page.
The following environment specifications apply to all modules:
Table 11: Specifications for XTM-905 and All XPA-xxx-x Modules

| Specification | Module | Description |
| :---: | :---: | :---: |
| Operating Environment | XTM-905 and XPx-xxx-x | $\begin{aligned} & 0 \text { to }+50^{\circ} \mathrm{C}\left(+32 \text { to }+122^{\circ} \mathrm{F}\right) \\ & 10 \text { to } 90 \% \mathrm{RH} \text {, non-condensing } \end{aligned}$ |
|  | XPA-4xx-x | $+5 \text { to }+40^{\circ} \mathrm{C}\left(+41 \text { to }+104^{\circ} \mathrm{F}\right)$ <br> 10 to $90 \%$ RH, non-condensing |
| Storage Environment | All modules | -40 to $+70^{\circ} \mathrm{C}\left(-40\right.$ to $\left.+158^{\circ} \mathrm{F}\right)$ |
| Weight | XTM-905 | 150 grams (5.3 ounces) |
|  | XPA-xxx-x without disconnect terminals | 237 grams (8.4 ounces) |
|  | XPA-xxx-x with disconnect terminals | 322 grams (11.4 ounces) |
|  | Other expansion modules (XPx-xxx-x ) without disconnect terminals | 163 grams (5.8 ounces) |
|  | Other expansion modules (XPx-xxx-x ) with disconnect terminals | 248 grams (8.8 ounces) |
| Agency Compliance | All Modules: CE Directive 89/336/EEC, EN 50081-1, EN 50082-1 |  |
|  | XPM, XPL, and XPE only: CE Directive 73/23/EEC EN 60730 |  |
|  | XTM-905 and XPx-xxx-x, except XPA-4xx-x: <br> UL Listed, CSA Certified, FCC Compliant |  |



Figure 28: XTM-905-5

Table 12: XTM-905-5 Specifications

| Specification | Description |
| :---: | :---: |
| Electrical Requirements | 24 VAC $\pm 15 \%, 50-60 \mathrm{~Hz}$ |
| Power Consumption | 5 VA |
| Terminations |  |
| Power Supply | 1.0... $1.5 \mathrm{~mm}^{2}$ (16 AWG) stranded cable $1.0 \ldots 2.5 \mathrm{~mm}^{2}$ (16... 14 AWG) solid cable |
| XT Bus | $0.5 \ldots 1.5 \mathrm{~mm}^{2}(20 \ldots 16) \text { AWG }$ <br> RS-485 cable <br> Two twisted pair cables, 120 ohms impedance |
| XPx Bus | 5-pin ribbon cable provided with XPx modules |
| Module Supply Bus (24 VAC) | 5-pin ribbon cable provided with XPx modules |
| XT Bus | RS-485; 9600 baud; opto-isolated |
| LED Indicators (red) | Power On (flashing = no communication or configuration error) <br> Receive Data <br> Transmit Data |

XPA-821-5,
XPA-831-5
(Europe Only)


Figure 29: XPA-821-5, XPA-831-5
Table 13: XPA-821-5, XPA-831-5 Specifications

| Specification | Description |
| :---: | :---: |
| Electrical Requirements | 24 VAC $\pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 6 VA |
| Terminations |  |
| Inputs/Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20... 16 AWG) stranded cable <br> $0.5 . .2 .5 \mathrm{~mm}^{2}$ (20... 14 AWG ) solid cable (XPA-831 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5 -pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Analog Inputs | Six inputs, 10-bit resolution, jumper selectable: <br> - 0-10V, > 300K ohm impedance, Accuracy: 100 mV <br> - 0/4-20 mA, 100 ohm impedance, Accuracy: 300 microamperes <br> - RTD (Ni1000, Pt1000, A99), Accuracy: $1^{\circ} \mathrm{C}$ at $25^{\circ} \mathrm{C}$ |
| Analog Outputs | Two outputs, jumper selectable: <br> - 0-10 VDC, (10 mA), Accuracy: 100 mV <br> - 0/4-20 mA, maximum 500 ohms, Accuracy: 200 microamperes |
| LED Indicators (red) | Each output level indicated by two LEDs, one for $0 \%$ and one for $100 \%$. <br> The LEDs are equally bright at $50 \%$ output. <br> Note: There are no Manual Override switches on this module. |
| Active Sensor Supply | 15 VDC, 30 mA |

Note: On older models, the AIC terminals may be marked $\perp$ and the AOC terminals may be marked $\downarrow$.

## XPA-421-5

(Europe Only),
XPA-431-5
(Europe Only)


Figure 30: XPA-421-5, XPA-431-5

Table 14: XPA-421-5, XPA-431-5

| Specification | Description |
| :---: | :---: |
| Electrical Requirements | $24 \mathrm{VAC} \pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 6 VA |
| Terminations |  |
| Inputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20... 16 AWG) stranded cable <br> $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20... 14 AWG) solid cable (XPA-431 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5 -pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Analog Inputs | Four inputs, 10-bit resolution, selectable by terminals used: <br> - 0-10V, > 300K ohm impedance, Accuracy: 5 mV <br> - 0/4-20 mA, 100 ohm impedance, Accuracy: 20 microamperes <br> - RTD (Ni1000, Pt1000, A99, Pt100, Ni100), Accuracy: $0.3^{\circ} \mathrm{C}$ <br> - Potentiometer 5K ohms, Accuracy: 20 ohms |
| Active Sensor Supply | $15 \mathrm{VDC}, 20 \mathrm{~mA}$ |

Note: On older models the AIC terminals may be marked $\perp$.

XPA-442-5
(Europe Only),
XPA-452-5
(Europe Only)


Figure 31: XPA-442-5, XPA-452-5

Table 15: XPA-442-5, XPA-452-5 Specifications

| Specification | Description |
| :---: | :---: |
| Electrical Requirements | $24 \mathrm{VAC} \pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 10 VA |
| Terminations |  |
| Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20...16 AWG) <br> $0.5 . .2 .5 \mathrm{~mm}^{2}$ (20... 14 AWG ) solid cable (XPA-452 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5-pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Analog Outputs | Four outputs, selectable by terminals used: <br> - 0-10 VDC (10 mA), Accuracy: 100 mV <br> - 0/4-20 mA, maximum 500 ohms, Accuracy: 200 microamperes |
| LED Indicators (red) | Output level indicated by 11 LEDs, 0-100\%. LEDs also show selected output and Auto/Manual mode. |
| Manual Override | Four pushbuttons for Manual Override operation: <br> $\Leftrightarrow \quad$ Toggles between Status and Value display modes. <br> A/M Toggles selected output between Auto and Manual modes. <br> 仓/ᄀ Select previous/next output, or increase/decrease value. |

Note: On older models the Vn terminals may be marked Un, and the AOC terminals may be marked $\downarrow$.

## XPA-462-5

(Europe Only),
XPA-472-5
(Europe Only)


Figure 32: XPA-462-5, XPA-472-5

Table 16: XPA-462-5, XPA-472-5 Specifications

| Specification | Description |
| :---: | :---: |
| Electrical Requirements | 24 VAC $\pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 10 VA |
| Terminations |  |
| Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20...16 AWG) stranded cable <br> $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20... 14 AWG) solid cable (XPA-472 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5-pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Analog Outputs | Four outputs, selectable by terminals used: <br> - 0-10 VDC (10 mA), Accuracy: 100 mV <br> - 0/4-20 mA, maximum 500 ohms, Accuracy: 200 microamperes |
| LED Indicators (red) | Output level indicated by 11 LEDs, 0-100\%. LEDs show output number (AO1-AO4), followed by level of output in a continuous cycle. <br> Note: There are no Manual Override switches on this module. |

Note: On older models the Vn terminals may be marked Un and the AOC terminals may be marked $\downarrow$.


Figure 33: XPB-821-5, XPB-831-5

Table 17: XPB-821-5, XPB-831-5 Specifications

| Specification | Description |
| :---: | :---: |
| Electrical Requirements | 24 VAC $\pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 3 VA |
| Terminations |  |
| Inputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20...16 AWG) stranded cable $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20... 14 AWG) solid cable (XPB-831 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5 -pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Binary Inputs | Eight binary inputs from potential-free contacts, input resistance 7K ohms. Software configurable as Maintained or Pulse type. Software configurable as NO or NC for each input. Transition counter function: minimum 20 milliseconds on, 20 milliseconds off. |
| LED Indicators (red) | Each input indicated by an LED. <br> Note: There are no Manual Override switches on this module. |

XPM-401-5
(Europe Only),
XPM-411-5
(Europe Only)


Figure 34: XPM-401-5, XPM-411-5
Table 18: XPM-401-5, XPM-411-5 Specifications

| Specification | Requirements |
| :---: | :---: |
| Electrical Requirements | 24 VAC $\pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 4 VA |
| Terminations |  |
| Inputs/Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20... 16 AWG) stranded cable <br> $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20... 14 AWG) solid cable (XPM-411 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5-pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Binary Inputs | Four binary inputs from potential-free contacts, input resistance 7K ohms. Software configurable as Maintained or Pulse type. Software configurable as NO or NC for each input. Transition counter function: minimum. 20 milliseconds on, 20 milliseconds off. |
| Relay Outputs | Two binary outputs, momentary relays <br> Software configurable pulse time ( $5 \ldots 1275$ milliseconds), 20 milliseconds default <br> Contact voltage ratings: <br> - $250 \mathrm{VAC}, 750 \mathrm{VA}$, or <br> - 250 VDC, 30 W , or <br> - 24 V (AC/DC), 70 W |
| LED Indicators (green) | Each input and output indicated by a 24 VAC, VDC LED. |
| Manual Override | Four switches for Manual Override operation: <br> A/M Toggles output between Auto and Manual modes <br> 0/1 Momentarily sets output to indicated state |

XPM-421-5
(Europe Only),
XPM-431-5
(Europe Only)


Figure 35: XPM-421-5, XPM-431-5
Table 19: XPM-421-5, XPM-431-5 Specifications

| Specification | Description |
| :---: | :---: |
| Electrical Requirements | 24 VAC $\pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 4 VA |
| Terminations |  |
| Inputs/Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20...16 AWG) stranded cable <br> $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20... 14 AWG) solid cable (XPM-431 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5-pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Binary Inputs | Four binary inputs from potential-free contacts, input resistance 7K ohms. Software configurable as Maintained or Pulse type. Software configurable as NO or NC for each input. Transition counter function: minimum 20 milliseconds on, 20 milliseconds off. |
| Relay Outputs | Two binary outputs, momentary relays <br> Software configurable pulse time ( $5 \ldots 1275$ milliseconds), 20 milliseconds default <br> Contact voltage ratings: <br> - 250 VAC, 750 VA, or <br> - $250 \mathrm{VDC}, 30 \mathrm{~W}$, or <br> - 24 V (AC/DC), 70 W |
| LED Indicators (green) | Each input and output indicated by an LED. <br> Note: There are no Manual Override switches on this module. |



Figure 36: XPL-401-5, XPL-411-5
Table 20: XPL-401-5, XPL-411-5 Specifications

| Specification | Description |
| :---: | :---: |
| Electrical Requirements | 24 VAC $\pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 5 VA |
| Terminations |  |
| Inputs/Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20...16 AWG) stranded cable <br> $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20... 14 AWG) solid cable (XPL-411 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5 -pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Binary Inputs | Four binary inputs from potential-free contacts, input resistance 7K ohms. Software configurable as Maintained or Pulse type. Software configurable as NO or NC for each input. Transition counter function: minimum 20 milliseconds on, 20 milliseconds off. |
| Relay Outputs | Three binary outputs, magnetically latching relays Contact voltage ratings: <br> - 250 VAC, 750 VA, or <br> - $250 \mathrm{VDC}, 30 \mathrm{~W}$, or <br> - 24 V (AC/DC), 70 W |
| LED Indicators (green) | Each input and output indicated by an LED. |
| Manual Override | Three switches for Manual Override operation: <br> A/0/1 Sets output to Auto or indicated state in Manual mode. |

XPL-421-5
(Europe Only),
XPL-431-5
(Europe Only)


Figure 37: XPL-421-5, XPL-431-5

Table 21: XPL-421-5, XPL-431-5 Specifications

| Specifications | Description |
| :---: | :---: |
| Electrical Requirements | 24 VAC $\pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 5 VA |
| Terminations |  |
| Inputs/Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20...16 AWG) stranded cable <br> $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20... 14 AWG ) solid cable (XPL-431 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5 -pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Binary Inputs | Four binary inputs from potential-free contacts, input resistance 7 K ohms. Software configurable as Maintained or Pulse type. Software configurable as NO or NC for each input. Transition counter function: minimum 20 milliseconds on, 20 milliseconds off. |
| Relay Outputs | Three binary outputs, magnetically latching relays Contact voltage ratings: <br> - 250 VAC, 750 VA, or <br> - $250 \mathrm{VDC}, 30 \mathrm{~W}$, or <br> - 24 V (AC/DC), 70 W |
| LED Indicators (green) | Each input and output indicated by an LED. <br> Note: There are no Manual Override switches on this module. |



Figure 38: XPE-401-5, XPE-411-5
Table 22: XPE-401-5, XPE-411-5 Specifications

| Specifications | Description |
| :---: | :---: |
| Electrical Requirements | 24 VAC $\pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 5 VA |
| Terminations |  |
| Inputs/Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20...16 AWG) stranded cable <br> $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20... 14 AWG ) solid cable (XPE-411 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5-pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx-Bus | 5-pin ribbon cable provided with module |
| Binary Inputs | Four binary inputs from potential-free contacts, input resistance 7K ohms. Software configurable as Maintained or Pulse type. Software configurable as NO or NC for each input. Transition counter function: minimum 20 milliseconds on, 20 milliseconds off. |
| Relay Outputs | Three binary outputs, electrically latching relays Contact voltage ratings: <br> - 250 VAC, 750 VA , or <br> - $250 \mathrm{VDC}, 30 \mathrm{~W}$, or <br> - 24 V (AC/DC), 70 W |
| LED Indicators (green) | Each input and output indicated by an LED. |
| Manual Override | Three switches for Manual Override operation: <br> A/0/1 Sets output to Auto or indicated state in Manual mode. |

XPE-421-5
(Europe Only),
XPE-431-5
(Europe Only)


Figure 39: XPE-421-5, XPE-431-5
Table 23: XPE-421-5, XPE-431-5 Specifications

| Specifications | Description |
| :---: | :---: |
| Electrical Requirements | $24 \mathrm{VAC} \pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 5 VA |
| Terminations |  |
| Inputs/Outputs | 0.5...1.5 mm ${ }^{2}$ (20...16 AWG) stranded cable |
| Module Supply Bus (24 VAC) | $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20...14 AWG) solid cable (XPE-431 with disconnect terminals) |
| XPx Bus | 5-pin ribbon cable provided with module, end-of-bus jumper provided with module |
| Binary Inputs | Four binary inputs from potential-free contacts, input resistance 7K ohms. Software configurable as Maintained or Pulse type. Software configurable as NO or NC for each input. Transition counter function: minimum 20 milliseconds on, 20 milliseconds off. |
| Relay Outputs | Three binary outputs, electrically latching relays Contact voltage ratings: <br> - 250 VAC, 750 VA, or <br> - 250 VDC, 30 W , or <br> - 24 V (AC/DC), 70 W |
| LED Indicators (green) | Each input and output indicated by an LED. <br> Note: There are no Manual Override switches on this module. |



Figure 40: XPE-404-5, XPE-414-5

Table 24: XPE-404-5, XPE-414-5 Specifications

| Specifications | Description |
| :---: | :---: |
| Electrical Requirements | 24 VAC $\pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 6 VA |
| Terminations |  |
| Inputs/Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20...16 AWG) stranded cable <br> $0.5 . .2 .5 \mathrm{~mm}^{2}$ (20... 14 AWG ) solid cable (XPE-414 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5 -pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Binary Inputs | Four binary inputs from potential-free contacts, input resistance 7K ohms. Software configurable as Maintained or Pulse type. Software configurable as NO or NC for each input. Transition counter function: minimum 20 milliseconds on, 20 milliseconds off. |
| Relay Outputs | Four binary outputs, electrically driven relays. Software configurable as On/Off or Pulse type (5... 1275 milliseconds). |
| LED Indicators (green) | Contact voltage ratings: <br> - 250 VAC, 250 VA, or <br> - 250 VDC, 10 W , or <br> - 24 V (AC/DC), 20W |
| Manual Override | Each input and output indicated by an LED. <br> Four switches for Manual Override operation: <br> A/0/1 Sets output to Auto or indicated state in Manual mode. |

XPE-424-5
(Europe Only),
XPE-434-5
(Europe Only)


Figure 41: XPE-424-5, XPE-434-5
Table 25: XPE-424-5, XPE-434-5 Specifications

| Specification | Description |
| :---: | :---: |
| Electrical Requirements | $24 \mathrm{VAC} \pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 6 VA |
| Terminations |  |
| Inputs/Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20... 16 AWG) stranded cable <br> $0.5 . .2 .5 \mathrm{~mm}^{2}$ (20... 14 AWG ) solid cable (XPE-434 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5 -pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Binary Inputs | Four binary inputs from potential-free contacts, input resistance 7K ohms. Software configurable as Maintained or Pulse type. Software configurable as NO or NC for each input. Transition counter function: minimum 20 milliseconds on, 20 milliseconds off. |
| Relay Outputs | Four binary outputs, electrically driven relays. Software configurable as On/Off or Pulse Type (5... 1275 milliseconds). <br> Contact voltage ratings: <br> - $250 \mathrm{VAC}, 250 \mathrm{VA}$, or <br> - $250 \mathrm{VDC}, 10 \mathrm{~W}$, or <br> - 24 V (AC/DC), 20W |
| LED Indicators (green) | Each input and output indicated by an LED. <br> Note: There are no Manual Override switches on this module. |

## XPE-444-5

(Europe Only),
XPE-454-5
(Europe Only)


Figure 42: XPE-444-5, XPE-454-5

Table 26: XPE-444-5, XPE-454-5 Specifications

| Specifications | Description |
| :---: | :---: |
| Electrical Requirements | $24 \mathrm{VAC} \pm 15 \%, 50 / 60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 4 VA |
| Terminations |  |
| Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20... 16 AWG) stranded cable <br> $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20... 14 AWG ) solid cable (XPE-454 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5-pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Relay Outputs | Four binary outputs, electrically driven relays. Software configurable as On/Off or Pulse type (5... 1275 milliseconds). |
| LED Indicators (green) | Contact voltage ratings: <br> - $250 \mathrm{VAC}, 250 \mathrm{VA}$, or <br> - 250 VDC, 10 W , or <br> - 24 V (AC/DC), 20W |
| Manual Override | Each output indicated by an LED. <br> Four switches for Manual Override operation: <br> A/0/1 Sets output to Auto or indicated state in Manual mode. |

XPE-464-5
(Europe Only),
XPE-474-5
(Europe Only)


Figure 43: XPE-464-5, XPE-474-5
Table 27: XPE-464-5, XPE-474-5 Specifications

| Specifications | Description |
| :---: | :---: |
| Electrical Requirements | $24 \mathrm{VAC} \pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 4 VA |
| Terminations |  |
| Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20...16 AWG) stranded cable <br> $0.5 . .2 .5 \mathrm{~mm}^{2}$ (20... 14 AWG ) solid cable (XPE-474 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5-pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Relay Outputs | Four binary outputs, electrically driven relays. Software configurable as On/Off or Pulse type (5... 1275 milliseconds). <br> Contact voltage ratings: <br> - 250 VAC, 250 VA, or <br> - 250 VDC, 10 W , or <br> - 24 V (AC/DC), 20W |
| LED Indicators (green) | Each output indicated by an LED. <br> Note: There are no Manual Override switches on this module. |



Figure 44: XPT-401-5, XPT-411-5

Table 28: XPT-401-5, XPT-411-5 Specifications

| Specification | Description |
| :---: | :---: |
| Electrical Requirements | 24 VAC $\pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 2 VA |
| Terminations |  |
| Inputs/Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20...16 AWG) stranded cable <br> $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20... 14 AWG ) solid cable (XPT-411 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5-pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Binary Inputs | Four binary inputs from potential-free contacts, input resistance 7K ohms. Software configurable as Maintained or Pulse type. Software configurable as NO or NC for each input. Transition counter function: minimum 20 milliseconds on, 20 milliseconds off. |
| Triac Outputs | Four binary outputs, triacs <br> 24 VAC RMS +15\%/500 mA RMS <br> Software configurable as On/Off or Pulse type ( $5 . . .1275$ milliseconds). |
| LED Indicators (green) | Each input and output indicated by an LED. |
| Manual Override | Three switches for Manual Override operation: <br> A/0/1 Sets output to Auto or indicated state in Manual mode. |

XPT-421-5
(Europe Only),
XPT-431-5
(Europe Only)


Figure 45: XPT-421-5, XPT-431-5

Table 29: XPT-421-5, XPT-431-5 Specifications

| Specification | Description |
| :---: | :---: |
| Electrical Requirements | 24 VAC $\pm 15 \%, 50-60 \mathrm{~Hz}$ (via Module Supply Bus) |
| Power Consumption | 2 VA |
| Terminations |  |
| Inputs/Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20...16 AWG) stranded cable <br> $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20... 14 AWG ) solid cable (XPT-431 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5-pin ribbon cable provided with module, end-of-bus jumper provided with module |
| XPx Bus | 5-pin ribbon cable provided with module |
| Binary Inputs | Four binary inputs from potential-free contacts, input resistance 7K ohms. Software configurable as Maintained or Pulse type. Software configurable as NO or NC for each input. Transition counter function: minimum 20 milliseconds on, 20 milliseconds off. |
| Triac Outputs | Four binary outputs, triacs <br> 24 VAC RMS +15\%/500 mA RMS <br> Software configurable as On/Off or Pulse type (5... 1275 milliseconds). |
| LED Indicators (green) | Each input and output indicated by an LED. <br> Note: There are no Manual Override switches on this module. |



Figure 46: XPT-861-5, XPT-871-5
Table 30: XPT-861-5, XPT-871-5 Specifications

| Specifications | Description |
| :---: | :---: |
| Electrical Requirements | Power from XTM-905 |
| Terminations |  |
| Outputs | $0.5 \ldots 1.5 \mathrm{~mm}^{2}$ (20... 16 AWG) stranded cable <br> $0.5 \ldots 2.5 \mathrm{~mm}^{2}$ (20... 14 AWG) solid cable (XPT-871 with disconnect terminals) |
| Module Supply Bus (24 VAC) | 5-pin ribbon cable provided with module, end-of-bus jumper provided with module Note: 24 VAC is not used, but must be connected. |
| XPx Bus | 5-pin ribbon cable provided with module |
| Triac Outputs | Eight binary outputs, triacs <br> 24 VAC RMS +15\%/500 mA RMS <br> Software configurable as On/Off or Pulse type (5... 1275 milliseconds). |
| LED Indicators (green) | Each output indicated by an LED. <br> Note: There are no Manual Override switches on this module. |

## Commissioning and Troubleshooting

## Switch and Jumper Settings

The sections below describe the following switch and jumper settings, which must be made on two of the modules before power is applied:

- On the XTM-905, the extension module address must be set with the address switches at the bottom of the module.
- On the XPA-8x1 module, the types of analog inputs and outputs must be set with jumpers on the circuit board of the module.
All of these settings must comply with the software configuration settings. For all other modules, no hardware settings are necessary because all configuration is handled in software.

Set the XTM Module Address using the block of eight DIP switches next to the lower terminals on the XTM-905 module. The address must be unique on the network to which the XTM-905 is connected. This network includes the N2 Bus to which the DX controller is connected and the XT Bus of all other DX controllers on the N2 Bus.


Figure 47: Address Switch on the XTM-905 (address = 10 in the figure)

The switches are numbered 1 to 8 , and each switch represents one bit in an 8 -bit binary representation of the address, giving an address range of $0-255$. Binary representation means that setting a switch to On adds to the address a specific decimal amount corresponding to the position of the switch. The table below shows the switch numbers and the decimal amount each switch represents.

Table 31: XTM-905 Switch Numbers and their Decimal Amounts

|  | Switch <br> Number <br> $\mathbf{1}$ | Switch <br> Number <br> $\mathbf{2}$ | Switch <br> Number <br> $\mathbf{3}$ | Switch <br> Number <br> $\mathbf{4}$ | Switch <br> Number <br> $\mathbf{5}$ | Switch <br> Number <br> $\mathbf{6}$ | Switch <br> Number <br> $\mathbf{7}$ | Switch <br> Number <br> $\mathbf{8}$ |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Decimal <br> Amount | 1 | 2 | 4 | 8 | 16 | 32 | 64 | 128 |

For example, to set a decimal address of 119, you would set Switches 1, 2, $3,5,6$, and 7 to on $(1+2+4+16+32+64=119)$, as shown in the figure below:


Address $=119$
Figure 48: Address Switch Set to Address 119

XPA-8x1 Jumper Settings

Set the analog input and output types of the XPA-8x1 module by setting jumpers on the circuit board of the module. Make all jumper settings before installing the module and before you apply power to the module. Remove the cover of the module by carefully prying it loose from the four retaining lugs located on the sides of the cover.


Figure 49: Jumper Details for the Older Version of XPA-8x1
Note: On older models, the AIC terminals may be marked $\perp$ and the AOC terminals may be marked $\perp$.


Figure 50: Jumper Details for the New Version of XPA-8x1
Notes: Set the Analog Input Type for each of AI1 to AI6 using one jumper per input in each respective position marked 1 to 6 on the corresponding jumper block. Place a jumper on the upper two pins to set an RTD resistive sensor input. Place a jumper on the lower two pins to set a $0-20 \mathrm{~mA}$ current input. Remove the jumper completely to set a $0-10 \mathrm{~V}$ input.
A maximum of 30 mA is available from the 15 V supply of the module.

Set the Analog Output Type for each of AO7 and AO8 using jumpers marked 7 and 8 on the corresponding jumper block. Place the jumpers as shown in the figure above for the required output type. Two jumpers are required for a $0-20 \mathrm{~mA}$ output and one jumper for a $0-10 \mathrm{~V}$ output.

## Power Up

After inspecting the field wiring, switch and jumper settings, and the XT Bus cabling, power may be applied to the XTM-905. If the software configuration has not yet been downloaded to the XTM (stored in non-volatile EEPROM), take the necessary steps using the GX-9100 Graphic Configuration software (GX Tool).
At power up, the XTM performs a configuration check, comparing the software defined configuration with the number and types of expansion modules actually connected to the XTM. If the configurations do not match, a configuration error will be indicated by the power LED of the XTM (see the following $L E D s$ section). The LED indicators on the front of the XTM- 905 module can be used to determine that the XTM is functioning properly.

LEDs
There are three LEDs on the front of the XTM-905 module: Power $(P W R)$, Receive Data $(R D)$, and Transmit Data (TD).


Figure 51: LEDs on the Front of the XTM-905
When power is applied to the XTM-905, the power LED indicates the following conditions:

- The power LED will light up continuously if the XTM has established good communications with the DX controller over the serial link (XT Bus), and there are no configuration errors.
- The power LED will flash at a frequency of about once per second if there is no communication with the the DX controller.
- The power LED will flash at a frequency of about twice per second if communications with the the DX controller are good but there is a configuration error.
The Receive Data (RD) LED lights to indicate that data is on the XT Bus. The Transmit Data (TD) LED lights to indicate that the XTM is responding on the XT Bus.
If there is a communications fault, you should check the XT Bus cabling, and also make sure that the address setting on the XTM agrees with the XTM address configured in the DX controller.

If there is a configuration error, make sure that the software configuration being downloaded to the XTM agrees with the actual types and number of expansion modules connected to the XTM. Any error in the configuration is also indicated in Items OPMO (dec. 01) and I2CE (dec. 02). (See XTM-905 Configuration Settings and Appendix A: Item Table for details). Another possible cause of this error could be an improperly seated ribbon cable connecting the expansion module communications bus.

Power Watchdog Loopback Jumper

The power watchdog circuit checks that power is getting to all modules; the XTM will not respond if there is a problem. For the power watchdog circuit to operate properly, you must make sure that the last expansion module connected to the XTM has the loopback (end-of-bus) jumper installed in the correct position on its connector for the 24 VAC module supply bus:


Figure 52: Power Watchdog Loopback Jumper on Last Module Connected to XTM-905

## Supply Protection

All modules are equipped with a protective device to limit the current drawn from the 24 VAC supply to approximately 500 mA in the event of an internal failure or an external short circuit due to incorrect wiring to the binary input terminals, which have the same common as the 24 VAC supply. If a module is not working (no LEDs show when the input or output is active), check the wiring. If the wiring is correct, replace the module.

Connect an RS-232-C/RS-485 converter (type MM-CVT101-x in North America and type IU-9100-810x in Europe) to one of the serial communication ports (COM1 or COM2) of the personal computer on which the GX Tool is running. Connect the N2 Bus of the DX to the converter unit connected to the PC.

Set the address switches and jumpers on the DX controller and XT/XTM devices as required, and connect the XT/XTM devices to the XT Bus of the DX. (See the DX-9100 Extended Digital Controller Technical Bulletin [LIT-6364020] for details.)

If the DX and XT/XTM devices are installed and wired, verify all field wiring and sensor voltage/current signals. It is recommended that controlled devices be isolated during download and initial startup.

IMPORTANT: Do not download an untested configuration into an installed device. Test the configuration on a simulator panel before downloading.

Apply 24 VAC power to the DX controller and XT/XTM devices.
On the GX Tool, select Action, Download, and DX. Enter the DX address (0-255) in the Address field, and select the PC serial communication port (COM1 or COM2). Click on OK.

Checks are made before the data is downloaded to the controller, and a message appears on the screen if a value is outside the normal range for that parameter. The user may abort the download process and change the value in the configuration or press $<$ Enter $>$ to ignore the message and download the entered value.

When the download is complete, select Action, Download, and XT/XTM. Verify that the correct Port is selected and click on OK.

For subsequent downloads, where the XT/XTM addresses have not been changed, the loading can be done in one process by selecting Action, Download, and DX and XT/XTM.

## Download via DX Controller (RS-232-C Port)

Connect the serial communication port of the PC directly to the RS-232-C port of the DX controller. See the DX-9100 Extended Digital Controller Technical Bulletin (LIT-6364020) for details.

## Upload via a DX Controller

Only upload complete DX /XT/XTM configurations from the DX controller. Save the current configuration on the PC screen and select File, New, then Action, Upload, and DX and XT/XTM. Enter the DX controller address ( $0-255$ ) and PC port (COM1 or COM2). Click on OK.

Note: When uploading a configuration from an XTM, modules defined as XPM, XPL, or XPE-4x1 are shown with four outputs, although only two or three outputs are physically available.

Via the SX Tool XT-905 configuration data only can be changed item by item with the SX Tool. It is not possible to download or upload a complete configuration.

## Appendix A: Item Table

## Items

Floating Point Numbers

Each constant, variable, or parameter in an XTM-905 Extension Module can be addressed via an Item code. All Items are listed in the Item Table that follows.

Note: It is important to note that EEPROM Items only can be written approximately 10,000 times, so that write commands from cyclical processes in supervisory systems must be avoided. The DX controller does not write to EEPROM items except during a configuration download.

The format of any XTM-905 Item is described by the following types:
Float: Floating point number (2 bytes)
1 Byte: Unsigned integer number from 0 to 255
8 Bits: $\quad 8$ bits (1 byte) used to store logic states
2 Bytes: Unsigned integer number from 0 to 65,535
16 Bits: 16 bits ( 2 bytes) used to store logic states
4 Bytes: Unsigned integer number from 0 to 4,294,967,295

An XTM-905 floating point number consists of two bytes, which are bit encoded using the following format:


A number is normalized when the most significant bit of the mantissa is $\operatorname{set}(\mathrm{M} 10=1)$.

A number is zero when all bits of the mantissa are 0 .

The value of a number is:

$$
<N U M B E R>=<S I G N>* .<M A N T I S S A>* 2 \exp <E X P O N E N T>
$$

Examples:


Item Table
Abbreviations used in the Item Table (Table 32):
ADDRESS Dec. Decimal Item Address
Hex. Hexadecimal Item Address
TYPE Item Type as described previously under Item Type.
R/W Read/Write conditions:
$\boldsymbol{R} \quad$ Read Only Item
$\boldsymbol{R} / \boldsymbol{W} \quad$ Read/Write Item
$\boldsymbol{R} / \boldsymbol{W}(\boldsymbol{E}) \quad \mathrm{Read} /$ Write Item (in EEPROM)
CNF Configuration Item (in EEPROM)
TAG Name for Item or bit position within an Item. Note that in bit-addressed Items, not all bits have an explicit Tag.

Table 32: Item Table

| Address |  | Type | R/W | Tag | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Dec. | Hex. |  |  |  |  |
| 00 | 00 | 1 Byte | R | MODL | Device Model: 18 hex. for XTM-905 |
| 01 | 01 | 8 Bits | R/W | OPMO | Operation Mode (status) |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\mathrm{X} 1=1$ |  |  | Watchdog Test |
|  |  | X2 $=1$ |  |  | DO Error |
|  |  | X3 = 1 |  |  | DI Error |
|  |  | X4 = 1 |  |  | AI Error |
|  |  | X5 = 1 |  |  | AO Error |
|  |  | X6 |  |  | Unused (set to 0) |
|  |  | X7 | R | FAIL | XT Fail Mode (= XTS, Bit X2) |
|  |  | X8 = 1 |  | PWR | Power Fail or Communications Failure |
| 02 | 02 | 8 Bits | R | I2CE | Bus Error |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | X1 = 1 |  |  | XP1: DO Error |
|  |  | X2 = 1 |  |  | XP2: DO Error |
|  |  | X3 = 1 |  |  | XP1: DI Error |
|  |  | X4 = 1 |  |  | XP2: DI Error |
|  |  | X5 = 1 |  |  | XP1: AI or Counter 1-4 Error |
|  |  | X6 = 1 |  |  | XP1: AO or Counter 5-8 Error |
|  |  | X7 = 1 |  |  | EEPROM Error |
|  |  | X8 = 1 |  | HARD | XPx Hardware not available |
| 03 | 03 | 1 Byte |  |  | Unused |
| 04 | 04 |  |  |  | Unused |
| to |  |  |  |  |  |
| 06 | 06 |  |  |  | Unused |
| 07 | 07 | 8 Bits | R/W | DOS1 | Binary Output Status XP1 (A/B) |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \hline X n=1 \\ & (n=1-4) \\ & \hline \end{aligned}$ |  | DOn | XP1A: Output \#n is On |
|  |  | $\begin{aligned} & \mathrm{Xn}=1 \\ & (\mathrm{n}=5-8) \end{aligned}$ |  | DOn | XP 1 B : Output \#n is On |
| 08 | 08 | 8 Bits | R/W | DOS2 | Binary Output Status XP2 (A/B) |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \hline X n=1 \\ & (n=1-4) \end{aligned}$ |  | DOn | XP2A: Output \#n is On |
|  |  | $\begin{aligned} & \hline X n=1 \\ & (n=5-8) \end{aligned}$ |  | DOn | XP2B: Output \#n is On |
| 09 | 09 | 8 Bits | R | DIS1 | Binary Input Status XP1 |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \hline X n=1 \\ & (n=1-8) \end{aligned}$ |  | DIn | XP1: Binary Input \#n is On |
| 10 | 0A | 8 Bits | R | DIS2 | Binary Input Status XP2 |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \hline X n=1 \\ & (n=1-8) \end{aligned}$ |  | DIn | XP2: Binary Input \#n is On |
| Continued on next page... |  |  |  |  |  |


| Address (Cont.) |  | Type | R/W | Tag | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Dec. | Hex. |  |  |  |  |
| 11 | OB | 16 Bits | R | AIS | Analog Input Status |
|  |  | X16 X15 X14 X13 X12 X11 X10 X9 X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | X1 = 1 |  | AlH1 | High Alarm Condition |
|  |  | X2 $=1$ |  | AIL1 | Low Alarm Condition |
|  |  | X3 $=1$ |  | AIH2 | High Alarm Condition |
|  |  | X4 = 1 |  | AIL2 | Low Alarm Condition |
|  |  | X5 = 1 |  | AlH3 | High Alarm Condition |
|  |  | X6 $=1$ |  | AIL3 | Low Alarm Condition |
|  |  | X7 = 1 |  | AIH4 | High Alarm Condition |
|  |  | X8 $=1$ |  | AIL4 | Low Alarm Condition |
|  |  | X9 = 1 |  | AlH5 | High Alarm Condition |
|  |  | X10 = 1 |  | AIL5 | Low Alarm Condition |
|  |  | X11 $=1$ |  | AlH6 | High Alarm Condition |
|  |  | X12 = 1 |  | AIL6 | Low Alarm Condition |
|  |  | X13 = 1 |  | AlH7 | High Alarm Condition |
|  |  | X14 = 1 |  | AIL7 | Low Alarm Condition |
|  |  | X15 = 1 |  | AlH8 | High Alarm Condition |
|  |  | X16 = 1 |  | AIL8 | Low Alarm Condition |
| 12 | OC | Float | R | Al1 | Analog Input Value 1 |
| 13 | OD | Float | R | Al2 | Analog Input Value 2 |
| 14 | OE | Float | R | Al3 | Analog Input Value 3 |
| 15 | OF | Float | R | Al4 | Analog Input Value 4 |
| 16 | 10 | Float | R | AI5 | Analog Input Value 5 |
| 17 | 11 | Float | R | Al6 | Analog Input Value 6 |
| 18 | 12 | Float | R | Al7 | Analog Input Value 7 |
| 19 | 13 | Float | R | Al8 | Analog Input Value 8 |
| 20 | 14 | Float | R/W | AO1 | Analog Output Value 1 |
| 21 | 15 | Float | R/W | AO2 | Analog Output Value 2 |
| 22 | 16 | Float | R/W | AO3 | Analog Output Value 3 |
| 23 | 17 | Float | R/W | AO4 | Analog Output Value 4 |
| 24 | 18 | Float | R/W | AO5 | Analog Output Value 5 |
| 25 | 19 | Float | R/W | AO6 | Analog Output Value 6 |
| 26 | 1A | Float | R/W | AO7 | Analog Output Value 7 |
| 27 | 1B | Float | R/W | AO8 | Analog Output Value 8 |
| 28 | 1C |  |  |  | Unused |
| to |  |  |  |  |  |
| 31 | 1F |  |  |  | Unused |
| 32 | 20 | 4 Bytes | R/W | CNT1 | DI1 Pulse Count - XP1 |
| 33 | 21 | 4 Bytes | R/W | CNT2 | DI2 Pulse Count - XP1 |
| 34 | 22 | 4 Bytes | R/W | CNT3 | DI3 Pulse Count - XP1 |
| 35 | 23 | 4 Bytes | R/W | CNT4 | DI4 Pulse Count - XP1 |
| 36 | 24 | 4 Bytes | R/W | CNT5 | DI5 Pulse Count - XP1 |
| Continued on next page... |  |  |  |  |  |


| Address (Cont.) |  | Type | R/W | Tag | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Dec. | Hex. |  |  |  |  |
| 37 | 25 | 4 Bytes | R/W | CNT6 | DI6 Pulse Count - XP1 |
| 38 | 26 | 4 Bytes | R/W | CNT7 | DI7 Pulse Count - XP1 |
| 39 | 27 | 4 Bytes | R/W | CNT8 | DI8 Pulse Count - XP1 |
| 40 | 28 | 8 Bits | CNF | MOE1 | Manual Override Enable XP1 |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \hline X n=0 \\ & (n=1-8) \\ & \hline \end{aligned}$ |  |  | DOn = Supervisory and Standalone |
|  |  | $\mathrm{Xn}=1$ |  |  | DOn = Standalone Only |
|  |  |  |  |  | (Note: All bits set to 0 or 1 by GX Tool.) |
| 41 | 29 | 8 Bits | CNF | MOE2 | Manual Override Enable XP2 |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \hline X n=0 \\ & (n=1-8) \\ & \hline \end{aligned}$ |  |  | DOn = Supervisory and Standalone |
|  |  | Xn = 1 |  |  | DOn = Standalone Only |
|  |  |  |  |  | (Note: All bits set to 0 or 1 by GX Tool.) |
| 42 | 2A | 8 Bits | CNF | DMI1 | Display Manual Override Status in DIS1 |
|  |  | $0000 \times 4 \times 3 \times 2 \times 1$ |  |  |  |
|  |  | $\begin{aligned} & \hline X n=0 \\ & (n=1-4) \\ & \hline \end{aligned}$ |  |  | DIn = Digital Input Status |
|  |  | $\mathrm{Xn}=1$ |  |  | DIn = Manual Override Status DOn+4 |
|  |  | $\begin{aligned} & \mathrm{Xn} \\ & (\mathrm{n}=5-8) \end{aligned}$ |  |  | Unused |
|  |  |  |  |  | (Note: All bits set to 0 or 1 by GX Tool.) |
| 43 | 2B | 8 Bits | CNF | DMI2 | Display Manual Override Status in DIS2 |
|  |  | 0000 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \mathrm{Xn}=0 \\ & (\mathrm{n}=1-4) \end{aligned}$ |  |  | DIn = Digital Input Status |
|  |  | $\mathrm{Xn}=1$ |  |  | DIn = Manual Override Status DOn+4 |
|  |  | $\begin{aligned} & \mathrm{Xn} \\ & (\mathrm{n}=5-8) \end{aligned}$ |  |  | Unused |
|  |  |  |  |  | (Note: All bits set to 0 or 1 by GX Tool.) |
| 44 | 2C |  |  |  | Unused (set to 0) |
| 45 | 2D |  |  |  | Unused (set to 0) |
| 46 | 2E | 8 Bits | CNF | NOC1 | Normally Open/Normally Closed Contact XP1 |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \hline \mathrm{Xn}=0 \\ & (\mathrm{n}=1-8) \end{aligned}$ |  |  | XP1: DIn = Normally Open |
|  |  | $\mathrm{Xn}=1$ |  |  | XP1: DIn = Normally Closed |
| 47 | 2F | 8 Bits | CNF | NOC2 | Normally Open/Normally Closed Contact XP2 |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \hline X n=0 \\ & (n=1-8) \\ & \hline \end{aligned}$ |  |  | XP2: DIn = Normally Open |
|  |  | $\mathrm{Xn}=1$ |  |  | XP2: DIn = Normally Closed |
| 48 | 30 | 1 Byte Int | CNF | PC1 | Prescaler DI1 Counter (default = 1) |
| 49 | 31 | 1 Byte Int | CNF | PC2 | Prescaler DI2 Counter (default = 1) |
| Continued on next page . . . |  |  |  |  |  |


| Address (Cont.) |  | Type | R/W | Tag | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Dec. | Hex. |  |  |  |  |
| 50 | 32 | 1 Byte Int | CNF | PC3 | Prescaler DI3 Counter (default = 1) |
| 51 | 33 | 1 Byte Int | CNF | PC4 | Prescaler DI4 Counter (default = 1) |
| 52 | 34 | 1 Byte Int | CNF | PC5 | Prescaler DI5 Counter (default = 1) |
| 53 | 35 | 1 Byte Int | CNF | PC6 | Prescaler DI6 Counter (default = 1) |
| 54 | 36 | 1 Byte Int | CNF | PC7 | Prescaler DI7 Counter (default = 1) |
| 55 | 37 | 1 Byte Int | CNF | PC8 | Prescaler DI8 Counter (default = 1) |
| 56 | 38 | 1 Byte | CNF | DIL1 | Internal use only |
| 57 | 39 | 1 Byte | CNF | DIL5 | Internal use only |
| 58 | 3A | 1 Byte | CNF | DIL9 | Internal use only |
| 59 | 3B | 1 Byte | CNF | DILD | Internal use only |
| 60 | 3C | 1 Byte | CNF | DOL1 | Internal use only |
| 61 | 3D | 1 Byte | CNF | DOL5 | Internal use only |
| 62 | 3E | 1 Byte | CNF | DOL9 | Internal use only |
| 63 | 3F | 1 Byte | CNF | DOLD | Internal use only |
| 64 | 40 | 8 Bits | CNF | DIT1 | Binary Input Type XP1 (A/B) |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \mathrm{Xn}=0 \\ & (\mathrm{n}=1-8) \end{aligned}$ |  |  | XP1: DIn = Maintained Contact (default) |
|  |  | Xn = 1 |  |  | XP1: Dln = Pulse Contact |
| 65 | 41 | 8 Bits | CNF | DIT2 | Binary Input Type XP2 (A/B) |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \mathrm{Xn}=0 \\ & (\mathrm{n}=1-8) \end{aligned}$ |  |  | XP2: DIn = Maintained Contact (default) |
|  |  | Xn = 1 |  |  | XP2: DIn = Pulse Contact |
| 66 | 42 | 8 Bits | CNF | DOT1 | Binary Output Type XP1 (A/B) |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  | (XPE-4x4 and XPT only) |
|  |  | $\begin{aligned} & \mathrm{Xn}=0 \\ & (\mathrm{n}=1-8) \end{aligned}$ |  |  | XP1: DOn = ON/OFF Type (default) |
|  |  | Xn = 1 |  |  | XP1 : DOn = Pulse Type |
| 67 | 43 | 8 Bits | CNF | DOT2 | Binary Output Type XP2 (A/B) |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  | (XPE-4x4 and XPT only) |
|  |  | $\begin{aligned} & \mathrm{Xn}=0 \\ & (\mathrm{n}=1-8) \end{aligned}$ |  |  | XP2: DOn = ON/OFF Type (default) |
|  |  | Xn = 1 |  |  | XP2: DOn = Pulse Type |
| 68 | 44 | 1 Byte | CNF | DOPT | Binary Output Pulse Time ( 5 milliseconds) (default value of $4=20$ milliseconds) |
| 69 | 45 | 8 Bits | CNF | XTS | XTM-905 Type Settings |
|  |  | X8 X7 X6 $000 \times 2 \times 1$ |  |  |  |
|  |  | X1 $=0$ |  |  | 50 Hz Power Line (default) |
|  |  | $\mathrm{X} 1=1$ |  |  | 60 Hz Power Line |
|  |  | X2 $=0$ |  |  | Output Reset on communication failure |
|  |  | X2 = 1 |  |  | Output Hold on communication failure (default) |
|  |  | $\begin{aligned} & \mathrm{X} 5, \mathrm{X} 4, \\ & \mathrm{X} 3 \\ & \hline \end{aligned}$ |  |  | Internal use only (must be set to 0) |
|  |  | X8 X7 X6 $=000$ |  |  | Counters on XP1 or XP1A (default - set by GX Tool) |
| Continued on next page ... |  |  |  |  |  |


| Address (Cont.) |  | Type | R/W | Tag | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Dec. | Hex. |  |  |  |  |
| 70 | 46 | 8 Bits | CNF | DOR1 | Binary Output Restore XP1 (A/B) |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \hline X n=0 \\ & (n=1-8) \\ & \hline \end{aligned}$ |  |  | Reset DOn to 0 at power up |
|  |  | Xn = 1 |  |  | Restore DOn at power up (default) |
| 71 | 47 | 8 Bits | CNF | DOR2 | Binary Output Restore XP2 (A/B) <br> (Note: All bits set to 0 or 1 by GX Tool.) |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\begin{aligned} & \hline X n=0 \\ & (n=1-8) \end{aligned}$ |  |  | Reset DOn to 0 at power up |
|  |  | Xn = 1 |  |  | Restore DOn at power up (default) |
| 72 | 48 | 8 Bits | CNF | COL1 | Counter Limit CNT1-CNT4 <br> (Note: All bits set to 0 or 1 by GX Tool.) |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | X2 X1 |  |  | Counter Limit CNT1, 11 = 9999999 (default - set by GX Tool) |
|  |  | X4 X3 |  |  | Counter Limit CNT2 (as X2 X1) |
|  |  | X6 X5 |  |  | Counter Limit CNT3 (as X2 X1) |
|  |  | X8 X7 |  |  | Counter Limit CNT4 (as X2 X1) |
| 73 | 49 | 8 Bits | CNF | COL2 | Counter Limit CNT5-CNT8 |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | X2 X1 |  |  | Counter Limit CNT5, 11 = 9999999 (default - set by GX Tool) |
|  |  | X4 X3 |  |  | Counter Limit CNT6 (as X2 X1) |
|  |  | X6 X5 |  |  | Counter Limit CNT7 (as X2 X1) |
|  |  | X8 X7 |  |  | Counter Limit CNT8 (as X2 X1) |
| 74 | 4A | 1 Byte | CNF |  | Internal use only |
| 75 | 4B | 1 Byte | CNF | AI2C | Internal use only |
| 76 | 4C | 1 Byte | CNF | AMOD | Internal use only |
| Continued on next page ... |  |  |  |  |  |


| Address (Cont.) |  | Type | R/W | Tag | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Dec. | Hex. |  |  |  |  |
| 77 | 4D | 8 Bits | CNF | IOMAP | Extension Module I/O Map |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | X1 $=0$ |  |  | XP1A : I/O1 and I/O2 Not Used |
|  |  | $\mathrm{X} 1=1$ |  |  | XP1A : I/O1 and I/O2 Used |
|  |  | X2 $=0$ |  |  | XP1A : I/O3 and I/O4 Not Used |
|  |  | X2 = 1 |  |  | XP1A : I/O3 and I/O4 Used |
|  |  | X3 $=0$ |  |  | XP1B : I/O5 and I/O6 Not Used |
|  |  | X3 = 1 |  |  | XP1B : I/O5 and I/O6 Used |
|  |  | X4 $=0$ |  |  | XP1B : I/O7 and I/O8 Not Used |
|  |  | X4 $=1$ |  |  | XP1B : I/O7 and I/O8 Used |
|  |  | X5 $=0$ |  |  | XP2A : I/O1 and I/O2 Not Used |
|  |  | X5 = 1 |  |  | XP2A : I/O1 and I/O2 Used |
|  |  | X6 = 0 |  |  | XP2A : I/O3 and I/O4 Not Used |
|  |  | X6 = 1 |  |  | XP2A : I/O3 and I/O4 Used |
|  |  | X7 = 0 |  |  | XP2B : I/O5 and I/O6 Not Used |
|  |  | X7 = 1 |  |  | XP2B : I/O5 and I/O6 Used |
|  |  | X8 $=0$ |  |  | XP2B : I/O7 and I/O8 Not Used |
|  |  | X8 = 1 |  |  | XP2B : I/O7 and I/O8 Used |
| 78 | 4E | 8 Bits | CNF | IOTYP | Extension Module I/O Type |
| 0000 X4 X3 X2 X1 |  |  |  |  |  |
|  |  | $\mathrm{X} 1=0$ |  |  | XP1A : I/O1 and I/O2 Digital |
|  |  | $\mathrm{X} 1=1$ |  |  | XP1A : I/O1 and I/O2 Analog |
|  |  | X2 $=0$ |  |  | XP1A : I/O3 and I/O4 Digital |
|  |  | X2 = 1 |  |  | XP1A : I/O3 and I/O4 Analog |
|  |  | X3 $=0$ |  |  | XP1B : I/O5 and I/O6 Digital |
|  |  | X3 $=1$ |  |  | XP1B : I/O5 and I/O6 Analog |
|  |  | X4 $=0$ |  |  | XP1B : I/O7 and I/O8 Digital |
|  |  | X4 = 1 |  |  | XP1B : I/O7 and I/O8 Analog |
|  |  | X8...X5 |  |  | Not Used |
| Continued on next page . . . |  |  |  |  |  |


| Address (Cont.) |  | Type | R/W | Tag | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Dec. | Hex. |  |  |  |  |
| 79 | 4F | 8 Bits | CNF | IOMOD | Extension Module I/O Mode |
|  |  | X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | $\mathrm{X} 1=0$ |  |  | XP1A : I/O1 and I/O2 Input |
|  |  | $\mathrm{X} 1=1$ |  |  | XP1A : I/O1 and I/O2 Output |
|  |  | X2 $=0$ |  |  | XP1A : I/O3 and I/O4 Input |
|  |  | X2 $=1$ |  |  | XP1A : I/O3 and I/O4 Output |
|  |  | X3 $=0$ |  |  | XP1B : I/O5 and I/O6 Input |
|  |  | X3 $=1$ |  |  | XP1B : I/O5 and I/O6 Output |
|  |  | X4 $=0$ |  |  | XP1B : I/O7 and I/O8 Input |
|  |  | X4 $=1$ |  |  | XP1B : I/O7 and I/O8 Output |
|  |  | X5 = 0 |  |  | XP2A : I/O1 and I/O2 Input |
|  |  | X5 = 1 |  |  | XP2A : I/O1 and I/O2 Output |
|  |  | X6 $=0$ |  |  | XP2A : I/O3 and I/O4 Input |
|  |  | X6 $=1$ |  |  | XP2A : I/O3 and I/O4 Output |
|  |  | X7 $=0$ |  |  | XP2B : I/O5 and I/O6 Input |
|  |  | X7 $=1$ |  |  | XP2B : I/O5 and I/O6 Output |
|  |  | X8 $=0$ |  |  | XP2B : I/O7 and I/O8 Input |
|  |  | X8 = 1 |  |  | XP2B : I/O7 and I/O8 Output |
| 80 | 50 | 1 Byte |  |  | Spare |
| 81 | 51 | 8 Bits | CNF | DCM1 | Display Common Manual Override in DIS1 |
|  |  | 0000X4000 |  |  |  |
|  |  | X3...X1 |  |  | Not used |
|  |  | X4 = 0 * |  |  | Digital Input Status in DI4 of XP1 |
|  |  | X4 = ${ }^{*}$ |  |  | Common Manual Override Status in DI4 of XP1 |
|  |  | X8...X5 |  |  | Not used |
| 82 | 52 | 8 Bits | CNF | DCM2 | Display Common Manual Override in DIS2 |
|  |  | 0000X4000 |  |  |  |
|  |  | X3...X1 |  |  | Not used |
|  |  | X4 = 0* |  |  | Digital Input Status in D14 of XP2 |
|  |  | X4 = ${ }^{*}$ * |  |  | Common Manual Override Status in DI4 of Xp2 |
|  |  | X8...X5 |  |  | Not used |
| Continued on next page... |  |  |  |  |  |

* Bit X4 set to 0 or 1 by GX Tool.

| Address (cont.) |  | Type | R/W | Tag | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Dec. | Hex. |  |  |  |  |
| 83 | 53 | 8 bits | CNF | DML1 | Display Manual Override in DIS1 LEDs |
|  |  | $0000 \times 4 \times 3 \times 2 \times 1$ |  |  |  |
|  |  | $\begin{aligned} & \hline \mathrm{Xn}=0 \\ & (\mathrm{n}=1-4) \\ & \hline \end{aligned}$ |  |  | LED (DIN) shows Digital Input Status |
|  |  | $\mathrm{Xn}=1$ |  |  | LED (DIN) shows Manual Override Status (DOn+4) (if selected in DMI1 or DCM1) |
|  |  | $\begin{aligned} & \mathrm{Xn} \\ & (\mathrm{n}=5-8) \end{aligned}$ |  |  | Unused |
| 84 | 54 | 8 bits | CNF | DML2 | Display Manual Override in DIS2 LEDs |
|  |  | $0000 \times 4 \times 3 \times 2 \times 1$ |  |  |  |
|  |  | $\begin{aligned} & \mathrm{Xn}=0 \\ & (\mathrm{n}=1-4) \end{aligned}$ |  |  | LED (DIN) shows Digital Input Status |
|  |  | $\mathrm{Xn}=1$ |  |  | LED (DIN) shows Manual Override Status (DOn+4) (if selected in DMI2 or DCM2) |
|  |  | $\begin{aligned} & \mathrm{Xn} \\ & (\mathrm{n}=5-8) \end{aligned}$ |  |  | Unused |
| 85 | 55 | 1 Byte | CNF |  | Not used (set to 0) |
| 86 | 56 | 2 Bytes | CNF | MTBC | Maximum Time Between Communications (default = 60 seconds) |
| 87 | 57 | 16 Bits | CNF | AOT | Analog Output Type |
|  |  | X16 X15 X14 X13 X12 X11 X10 X9 X8 X7 X6 X5 X4 X3 X2 X1 |  |  |  |
|  |  | X2 X1 Signal Analog Output \#1 |  |  |  |
|  |  | $=00$ |  |  | Output Disabled |
|  |  | = 01 |  |  | Output 0 to 10V |
|  |  | = 10 |  |  | Output 0 to 20 mA |
|  |  | = 11 |  |  | Output 4 to 20 mA |
|  |  | X4 X3 |  |  | Signal Analog Output 2 (as X2 X1) |
|  |  | X6 X5 |  |  | Signal Analog Output 3 (as X2 X1) |
|  |  | X8 X7 |  |  | Signal Analog Output 4 (as X2 X1) |
|  |  | X10 X9 |  |  | Signal Analog Output 5 (as X2 X1) |
|  |  | X12 X11 |  |  | Signal Analog Output 6 (as X2 X1) |
|  |  | X14 X13 |  |  | Signal Analog Output 7 (as X2 X1) |
|  |  | X16 X15 |  |  | Signal Analog Output 8 (as X2 X1) |
| Continued on next page... |  |  |  |  |  |


| Address (Cont.) |  | Type | R/W | Tag | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Dec. | Hex. |  |  |  |  |
| 88 | 58 | 16 Bits | CNF | AIT1 | Input Type of Analog Input 1 |
|  |  | $0 \times 1500 \times 12 \times 11 \times 10 \times 9 \times 8 \times 7 \times 6 \times 5 \times 4 \times 3 \times 2 \times 1$ |  |  |  |
|  |  | X4 X3 X2 X1 |  |  | Measurement Units |
|  |  | $=0000$ |  |  | Linear (active sensor) |
|  |  | = 0001 |  |  | Degrees Celsius (RTD) |
|  |  | = 0010 |  |  | Degrees Fahrenheit (RTD) |
|  |  | = 0011 |  |  | Linear (Potentiometer) |
|  |  | X5 = 1 |  |  | Enable Square Root of Input |
|  |  | $\mathrm{X} 6=1$ |  |  | Alarm on Unfiltered Value |
|  |  | X7 $=0$ |  |  | 0-10 Volts (default) or Potentiometer |
|  |  | X7 = 1 |  |  | 0-2 Volts, 0-20 mA or RTD |
|  |  | X8 = 1 |  |  | 20\% Suppression |
|  |  | X12 X11 X10 X9 |  |  | Linearization and Sensor Type |
|  |  | $=0000$ |  |  | Linear (active sensor) |
|  |  | = 0001 |  |  | Nickel 1000 Sensor (Johnson Controls) |
|  |  | $=0010$ |  |  | Nickel 1000 Extended Range (Johnson Controls) |
|  |  | = 0011 |  |  | A99 Sensor (Johnson Controls) |
|  |  | = 0100 |  |  | PT1000 Sensor (DIN) |
|  |  | = 0101 |  |  | Nickel 1000 Sensor (L\&G) - XPA-4x1 only |
|  |  | = 0110 |  |  | Nickel 1000 Sensor (DIN) - XPA-4x1 only |
|  |  | = 0111 |  |  | Unused |
|  |  | = 1000 |  |  | Potentiometer 5K ohms - XPA-4x1 only |
|  |  | = 1001 |  |  | PT100 Sensor (DIN) - XPA-4x1 only |
|  |  | = 1010 |  |  | Nickel 100 Sensor (DIN) - XPA-4x1 only |
|  |  | X15 = 0 |  |  | RTD 2- or 4-wire connection - XPA-4x1 only |
|  |  | X15 = 1 |  |  | RTD 3-wire connection - XPA-4x1 only |
| 89 | 59 | Float | CNF | HR1 | High Range Analog Input 1 (default = 100) |
| 90 | 5A | Float | CNF | LR1 | Low Range Analog Input 1 (default = 0) |
| 91 | 5B | Float | R/W (E) | HIA1 | High Alarm Limit Analog Input 1 (default =100) |
| 92 | 5C | Float | R/W (E) | LOA1 | Low Alarm Limit Analog Input 1 (default = 0) |
| 93 | 5D | Float | R/W (E) | ADF1 | Differential on Alarm Limit (default = 1) |
| 94 | 5E | Float | CNF | FTC1 | Filter Constant Analog Input 1 (default = 0) |
| 95 | 5F | Float | CNF | OFS1 | Analog Input Al1 Offset (default = 0) |
| 96 | 60 | 16 Bits | CNF | AIT2 | Input Type of Analog Input 2 (bits as AIT1) |
| 97 | 61 | Float | CNF | HR2 | High Range Analog Input 2 (default = 100) |
| 98 | 62 | Float | CNF | LR2 | Low Range Analog Input 2 (default = 0) |
| 99 | 63 | Float | R/W (E) | HIA2 | High Alarm Limit Analog Input 2 (default =100) |
| 100 | 64 | Float | R/W (E) | LOA2 | Low Alarm Limit Analog Input 2 (default = 0) |
| 101 | 65 | Float | R/W (E) | ADF2 | Differential on Alarm Limit (default = 1) |
| Continued on next page . . . |  |  |  |  |  |


| Address (Cont.) |  | Type | R/W | Tag | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Dec. | Hex. |  |  |  |  |
| 102 | 66 | Float | CNF | FTC2 | Filter Constant Analog Input 2 |
| 103 | 67 | Float | CNF | OFS2 | Analog Input AI2 Offset |
| 104 | 68 | 16 Bits | CNF | AIT3 | Input Type of Analog Input 3 (bits as AIT1) |
| 105 | 69 | Float | CNF | HR3 | High Range Analog Input 3 (default = 100) |
| 106 | 6A | Float | CNF | LR3 | Low Range Analog Input 3 (default = 0) |
| 107 | 6B | Float | R/W (E) | HIA3 | High Alarm Limit Analog Input 3 (default = 100) |
| 108 | 6C | Float | R/W (E) | LOA3 | Low Alarm Limit Analog Input 3 (default = 0) |
| 109 | 6D | Float | R/W (E) | ADF3 | Differential on Alarm Limit (default = 1) |
| 110 | 6E | Float | CNF | FTC3 | Filter Constant Analog Input 3 |
| 111 | 6F | Float | CNF | OFS3 | Analog Input AI3 Offset |
| 112 | 70 | 16 Bits | CNF | AIT4 | Input Type of Analog Input 4 (bits as AIT1) |
| 113 | 71 | Float | CNF | HR4 | High Range Analog Input 4 (default = 100) |
| 114 | 72 | Float | CNF | LR4 | Low Range Analog Input 4 (default = 0) |
| 115 | 73 | Float | R/W (E) | HIA4 | High Alarm Limit Analog Input 4 (default = 100) |
| 116 | 74 | Float | R/W (E) | LOA4 | Low Alarm Limit Analog Input 4 (default = 0) |
| 117 | 75 | Float | R/W (E) | ADF4 | Differential on Alarm Limit (default = 1) |
| 118 | 76 | Float | CNF | FTC4 | Filter Constant Analog Input 4 |
| 119 | 77 | Float | CNF | OFS4 | Analog Input AI4 Offset |
| 120 | 78 | 16 Bits | CNF | AIT5 | Input Type of Analog Input 5 (bits as AIT1) |
| 121 | 79 | Float | CNF | HR5 | High Range Analog Input 5 (default = 100) |
| 122 | 7A | Float | CNF | LR5 | Low Range Analog Input 5 (default = 0) |
| 123 | 7B | Float | R/W (E) | HIA5 | High Alarm Limit Analog Input 5 (default = 100) |
| 124 | 7C | Float | R/W (E) | LOA5 | Low Alarm Limit Analog Input 5 (default = 0) |
| 125 | 7D | Float | R/W (E) | ADF5 | Differential on Alarm Limit (default = 1) |
| 126 | 7E | Float | CNF | FTC5 | Filter Constant Analog Input 5 |
| 127 | 7F | Float | CNF | OFS5 | Analog Input AI5 Offset |
| 128 | 80 | 16 Bits | CNF | AIT6 | Input Type of Analog Input 6 (bits as AIT1) |
| 129 | 81 | Float | CNF | HR6 | High Range Analog Input 6 (default = 100) |
| 130 | 82 | Float | CNF | LR6 | Low Range Analog Input 6 (default = 0) |
| 131 | 83 | Float | R/W (E) | HIA6 | High Alarm Limit Analog Input 6 (default = 100) |
| 132 | 84 | Float | R/W (E) | LOA6 | Low Alarm Limit Analog Input 6 (default = 0) |
| 133 | 85 | Float | R/W (E) | ADF6 | Differential on Alarm Limit (default = 1) |
| 134 | 86 | Float | CNF | FTC6 | Filter Constant Analog Input 6 |
| 135 | 87 | Float | CNF | OFS6 | Analog Input AI6 Offset |
| 136 | 88 | 16 Bits | CNF | AIT7 | Input Type of Analog Input 7 (bits as AIT1) |
| 137 | 89 | Float | CNF | HR7 | High Range Analog Input 7 (default = 100) |
| 138 | 8A | Float | CNF | LR7 | Low Range Analog Input 7 (default = 0) |
| 139 | 8B | Float | R/W (E) | HIA7 | High Alarm Limit Analog Input 7 (default = 100) |
| 140 | 8C | Float | R/W (E) | LOA7 | Low Alarm Limit Analog Input 7 (default = 0) |
| 141 | 8D | Float | R/W (E) | ADF7 | Differential on Alarm Limit (default = 1) |
| 142 | 8E | Float | CNF | FTC7 | Filter Constant Analog Input 7 |
| Continued on next page ... |  |  |  |  |  |


| Address <br> (Cont.) | Type | R/W | Tag | Description |  |
| :--- | :--- | :--- | :--- | :--- | :--- |
| Dec. | Hex. |  |  |  |  |
| 143 | $8 F$ | Float | CNF | OFS7 | Analog Input AI7 Offset |
| 144 | 90 | 16 Bits | CNF | AIT8 | Input Type of Analog Input 8 (bits as AIT1) |
| 145 | 91 | Float | CNF | HR8 | High Range Analog Input 8 (default = 100) |
| 146 | 92 | Float | CNF | LR8 | Low Range Analog Input 8 (default = 0) |
| 147 | 93 | Float | R/W (E) | HIA8 | High Alarm Limit Analog Input 8 (default = 100) |
| 148 | 94 | Float | R/W (E) | LOA8 | Low Alarm Limit Analog Input 8 (default = 0) |
| 149 | 95 | Float | R/W (E) | ADF8 | Differential on Alarm Limit (default = 1) |
| 150 | 96 | Float | CNF | FTC8 | Filter Constant Analog Input 8 |
| 151 | 97 | Float | CNF | OFS8 | Analog Input AI8 Offset |
| 152 | 98 | Byte | CNF | AOR1 | Analog Output 1 Ramp Time (units of 5 milliseconds per 1\% <br> change, default = 0) |
| 153 | 99 | Byte | CNF | AOR2 | Analog Output 2 Ramp Time (units of 5 milliseconds per 1\% <br> change, default = 0) |
| 154 | 9 A | Byte | CNF | AOR3 | Analog Output 3 Ramp Time (units of 5 milliseconds per 1\% <br> change, default = 0) |
| 155 | $9 B$ | Byte | CNF | AOR4 | Analog Output 4 Ramp Time (units of 5 milliseconds per 1\% <br> change, default = 0) |
| 156 | $9 C$ | Byte | CNF | AOR5 | Analog Output 5 Ramp Time (units of 5 milliseconds per 1\% <br> change, default = 0) |
| 157 | $9 D$ | Byte | CNF | AOR6 | Analog Output 6 Ramp Time (units of 5 milliseconds per 1\% <br> change, default = 0) |
| 158 | $9 E$ | Byte | CNF | AOR7 | Analog Output 7 Ramp Time (units of 5 milliseconds per 1\% <br> change, default = 0) |
| 159 | $9 F$ | Byte | CNF | AOR8 | Analog Output 8 Ramp Time (units of 5 milliseconds per 1\% <br> change, default = 0) |

## Appendix B: Ordering Information

Table 33: XTM-905 and XPx-xxx Model Codes (North America)

| Model Code | Description |
| :--- | :--- |
| XTM-905-5 | Extension Module, XT Bus communication interface and 24 VAC supply |
| XPA-821-5 | Expansion Module Analog, six analog inputs, two analog outputs without manual override |
| XPB-821-5 | Expansion Module Binary, eight binary inputs |
| XPL-401-5 | Expansion Module Binary, four binary inputs, three binary outputs <br> (latching relays with manual override) |
| XPE-401-5 | Expansion Module Binary, four binary inputs, three binary outputs <br> (electrically maintained relays with manual override) |
| XPE-404-5 | Expansion Module Binary, four binary inputs, four binary outputs (common supply) <br> (electrically maintained relays with manual override, software configurable as On/Off or <br> pulse type) |
| XPT-401-5 | Expansion Module Binary, four binary inputs, four binary outputs <br> (24 VAC triacs with manual override) |
| XPT-861-5 | Expansion Module Binary, eight binary outputs (24 VAC triacs without manual override) |

Table 34: XPx-xxx-x Ordering Codes (Europe)

| Code | Module Type | Description |
| :---: | :---: | :---: |
| $\begin{aligned} & \hline \text { XPA-421-5 } \\ & \text { XPA-431-5 } \end{aligned}$ | Expansion Module Analog | 4 analog inputs (including PT100, Ni100, and 0-5K ohm) |
| $\begin{array}{\|l\|} \hline \text { XPA-442-5 } \\ \text { XPA-452-5 } \end{array}$ | Expansion Module Analog | 4 analog outputs with manual override |
| $\begin{array}{\|l\|} \hline \text { XPA-462-5 } \\ \text { XPA-472-5 } \\ \hline \end{array}$ | Expansion Module Analog | 4 analog outputs without manual override |
| XPA-831-5 | Expansion Module Analog | 6 analog inputs 2 analog outputs without manual override |
| XPB-831-5 | Expansion Module Binary | 8 binary inputs |
| $\begin{aligned} & \text { XPM-401-5 } \\ & \text { XPM-411-5 } \end{aligned}$ | Expansion Module Binary | 4 binary inputs <br> 2 binary outputs <br> (momentary relays with manual override) |
| XPL-411-5 | Expansion Module Binary | 4 binary inputs <br> 3 binary outputs <br> (latching relays with manual override) |
| $\begin{array}{\|l\|} \hline \text { XPL-421-5 } \\ \text { XPL-431-5 } \end{array}$ | Expansion Module Binary | 4 binary inputs <br> 3 binary outputs <br> (latching relays without manual override) |
| XPE-411-5 | Expansion Module Binary | 4 binary inputs <br> 3 binary outputs <br> (electrically maintained relays with manual override) |
| $\begin{aligned} & \text { XPE-421-5 } \\ & \text { XPE-431-5 } \end{aligned}$ | Expansion Module Binary | 4 binary inputs <br> 3 binary outputs <br> (electrically maintained relays without manual override) |
| XPE-414-5 | Expansion Module Binary | 4 binary inputs <br> 4 binary outputs (common supply) <br> (On/Off or pulse relays with manual override) |
| $\begin{aligned} & \text { XPE-424-5 } \\ & \text { XPE-434-5 } \end{aligned}$ | Expansion Module Binary | 4 binary inputs <br> 4 binary outputs (common supply) <br> (On/Off or pulse relays without manual override) |
| $\begin{aligned} & \text { XPE-444-5 } \\ & \text { XPE-454-5 } \end{aligned}$ | Expansion Module Binary | 4 binary outputs (common supply) (On/Off or pulse relays with manual override) |
| $\begin{aligned} & \text { XPE-464-5 } \\ & \text { XPE-474-5 } \end{aligned}$ | Expansion Module Binary | 4 binary outputs (common supply) (On/Off or pulse relays without manual override) |
| XPT-411-5 | Expansion Module Binary | 4 binary inputs <br> 4 binary outputs <br> (24 VAC triacs with manual override) |
| $\begin{array}{\|l\|} \hline \text { ХPT-421-5 } \\ \text { ХPT-431-5 } \end{array}$ | Expansion Module Binary | 4 binary inputs <br> 4 binary outputs <br> (24 VAC triacs without manual override) |
| XPT-871-5 | Expansion Module Binary | 8 binary outputs (24 VAC triacs without manual override) |

Note: The model numbers with a 0,2 , 4 , or 6 as the second digit are for modules with normal terminals; the model numbers with a $1,3,5$, or 7 as the second digit are for modules with disconnect terminals.

Table 35: Accessories Model Codes

| Model Code | Description |
| :--- | :--- |
| XST-101-0 | 50 DIN A4 sheets of blank stickers (12 per sheet) for module front panel |
| AS-ENC100-0 | Generic Enclosure Kit, Sheet Metal |
| EN-EWC10-0 | Single Enclosure, Plastic Universal Packaging Module (UPM), without Transformer |
| EN-EWC20-0 | UPM Dual Unit without Power Components |
| EN-EWC30-0 | UPM Triple Unit without Power Components |
| EN-EWC40-0 | UPM Quad Unit without Power Components |
| EN-EWC15-0 | Single Enclosure, Plastic UPM with 50 VA Transformer |
| EN-EWC25-0 | UPM Dual Unit with Power Entry Box and 50 VA Power Transformer |
| EN-EWC35-0 | UPM Triple Unit with Power Entry Box and 100 VA Power Transformer |
| EN-EWC45-0 | UPM Quad Unit with Power Entry Box and 100 VA Power Transformer |
| AS-XFR050-0* | 50 VA Transformer, Split Bobbin |
| AS-XFR010-1 | 100 VA Transformer, 120 VAC with Circuit Breaker, Split Bobbin, UL Recognized Class 2 |
| AS-XFR100-1* | 100 VA Transformer Kit, 120 VAC with Circuit Breaker, Split Bobbin |
| MW-MTOOL-0 | M-Tool package includes GX Tool Software and XTM Configurator software. |
| MW-MTOOL-6 | M-Tool software upgrade (The package upgrades customers from Configuration Tools to <br> M-Tool.) |

* These are the only transformers approved for UL 864 smoke control applicaions. Any UL Recognized Class 2 transformer may be used in UL 916 energy management applications.


## Notes

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