

WTF12G-3P2432







Photoelectric sensors TranspaTect, Photoelectric proximity sensor, Foreground suppression

Model Name > WTF12G-3P2432

Part No. > 1065719



At a glance

- · High-performance SICK technology
- · No reflectors required
- · Existing machine parts are used as reference target
- · AutoAdapt for continuous threshold adaptation in contaminated conditions
- PinPoint LED with bright and precise light spot
- · Easy-to-use teach-in button
- · Status LEDs visible from all sides
- · Rugged metal housing (PTFE coating available on request)

Your benefits

- · Reliable detection of transparent and semitransparent objects without a reflector
- · Reliable detection of objects regardless of color or surface qualities
- Freedom of machine design: no mounting system for the installation of a reflector required
- Quick commissioning: there is no need to mount a reflector or precisely adjust the sensor
- High operational safety: if the background becomes contaminated, object detection will continue uninterrupted
- Machine downtime is minimized: the integrated AutoAdapt function extends the time between cleanings
- Heightened productivity: mechanical and chemical ruggedness due to the metal housing



Illustration may differ

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Features

Sensor/detection principle: Photoelectric proximity sensor, Foreground suppression

Dimensions (W x H x D): 15.6 mm x 48.5 mm x 42 mm

Housing design (light emission):

Rectangular

Sensing range max.: 150 mm ... 700 mm ¹⁾
Sensing range: 0 mm ... 450 mm ²⁾

Type of light:

Light source:

Visible red light

Light source:

PinPoint LED

Teach-in: Single teach-in button

Adjustment: Teach-in

Light spot size (distance): Ø 8 mm (300 mm)

Mechanics/electronics

Supply voltage:

10 V DC ... 30 V DC $^{1)}$ \leq 5 Vpp $^{2)}$ \leq 55 mA $^{3)}$ Ripple: Power consumption: PNP Output type:

Output function: Complementary Light/dark switching Switching mode:

Output current Imax.: 100 mA 2 ms ⁴⁾ Response time: 250 Hz ⁵⁾ Switching frequency:

Connector M12, 4-pin A, C, D 6) 7) 8) Connection type:

Circuit protection:::

Protection class: Weight: 120 g Housing material: Metal **IP 66** Enclosure rating: **IP 67**

Special feature: For transparent objects

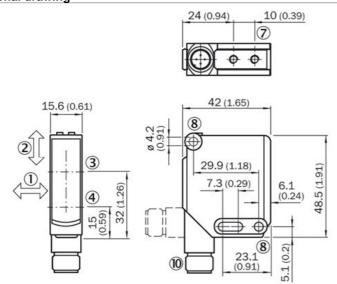
Ambient operating temperature: -40 °C ... +60 °C -40 °C ... +75 °C Ambient storage temperature:

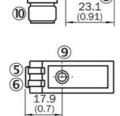
UL File No.: NRKH.E181493 & NRKH7.E181493

Signal voltage PNP HIGH/LOW: > Uv - 2,5 V/ca. 0 V

¹⁾ Limit values, operation in short-circuit protected network max. 8 A 2) May not exceed or fall short of V_S tolerances 3) Without load 4) Signal transit time with resistive load ⁵⁾ With light/dark ratio 1:1 ⁶⁾ A = V_S connections reverse-polarity protected ⁷⁾ C = interference suppression ⁸⁾ D = outputs overcurrent and short-circuit protected

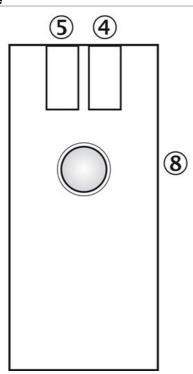
Dimensional drawing



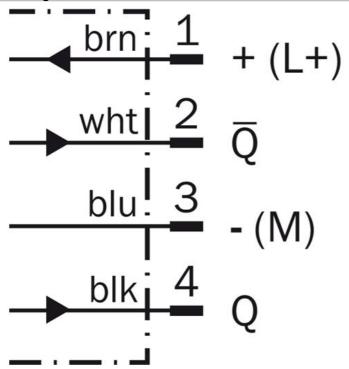


- |1| Recommended installation for the detection of transparent trays
- |2| Recommended installation for the detection of transparent bottles
- |3| Optical axis, receiver
- |4| Optical axis, sender
- |5| Status indicator LED green: power on
- |6| Status indicator LED, yellow: Status of received light beam
- |7| M4 threaded mounting hole, 4 mm deep
- |8| Mounting hole, Ø 4.2 mm
- |9| Adjustment sensing range: single teach-in button
- |10| Connection

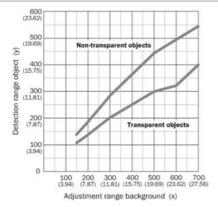
Adjustments possible



- |4| Status indicator LED green: power on
- |5| Status indicator LED, yellow: Status of received light beam
- |8| Adjustment sensing range: single teach-in button



Characteristic curve



Legend:

- x: Sensing range max. in mm (adjustment range background)
 - = Distance sensor / background
- y: Sensing range in mm (detection range object)
 = Maximum distance sensor / front edge of the object

Minimum distance sensor / background : 150 mm*

*) Referring to the background with 90 % remission equivalent to standard white DIN 5033 (i.e. glass-bead blasted stainless steel). The use of a shiry background can increase the minimum distance to the background (i.e. brushed and pickled stainless steel, minimum distance sensor to background: 300 mm).

How to use this diagram:

Measure the distance from the sensor to the metal surface in the background. This is the value for x (adjustment range background). If this is 500 mm for example, the maximum distance between the sensor and the leading edge of a transparent object is 300 mm. Australia

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